



Universidad de Granada

MASTER THESIS

DYNAMIC STIFFNESS OF A GRAVITY BASED FOUNDATION IN OFFSHORE STRUCTURE: DEPENDENCE OF SOIL PROPERTIES IN GLOBAL DAMPING

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Department of Structural Mechanics and Hydraulic Engineering
UNIVERSITY OF GRANADA 2016

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DAMPING

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September 2016

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Summary

Designing foundations for offshore wind turbines (OWT's) are challenging, in order to ensure reliable and cost-effective designs, the effects of the support structure and the subsoil on the natural vibration characteristics have to be taken into account during the dynamic simulation of the structural response.

The focus of this work is to evaluate the influence of the multi-layered strata on the magnitude of the soil-structure interaction (SSI) of gravity-based structure (GBS) foundations. To do so, a simplified model is proposed for the computation of impedance functions including the SSI effects. The result will be obtained using 3D boundary element program "BEASSI" and "SAP2000".

Acknowledgements

First and foremost, I would like to express my deepest gratitude to Prof. Alejandro E. Martínez Castro, for his invaluable guidance, cooperation and constant encouragement during the course of the project.

Thank you for being patient and helping me improve. Without his support, I could not have done what I was able to do.

And also I would especially like to thank to my family and all my friends for their support and constant encouragement I have gotten over the years, without them I would not find the courage to finish this thesis.

I want to dedicate this thesis to my grandparents, who are still waiting for my return to my homeland.

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CHAPTER 1

Introduction, objectives and methodology

1.1 Introduction

Modern wind turbines are constantly increasing in size with larger rotors and more powerful generators. The costs are kept as low as possible by reducing the overall weight, which leads to slender and flexible structures sensitive to the dynamic amplification of the response from wave- and wind-induced loads. This in turn necessitates a reliable estimate of the basic dynamic properties of the entire wind turbine structure in order to decrease the fatigue damage accumulation. In this regard, the wave propagation in the subsoil emitted from the vibrations on the soil-foundation interface is crucial to consider. To deal with this soil-structure interaction problem, sub-structuring technique is normally employed. In the application of sub-structuring technique, the surrounding soil of structural foundation is represented by an impedance matrix, which can then be combined into total stiffness matrix of finite element model of structure for soil-structure interaction analysis. Therefore, to effectively and efficiently generate impedance matrix is an important step for the soil-structure interaction analysis.

For evaluating the impedance of OWT foundations exist several methods, among these the finite-element method with radiating and transmitting boundary conditions suggested by Higdon [2,3] and Krenk [4], the boundary-element method, the domain-transformation method, analytical and semi analytical approaches. Based on transfer matrices for a layered half-space, originally proposed by Haskell [5] and Thomson [6], Andersen and Clausen [7], Andersen [8] and Damgaard et al. [9] used the domain-transformation method [10] for a rigid surface foundation on a horizontal viscoelastic stratum and proved that the impedance in terms of its magnitude and phase angle followed a second order polynomial without any resonance peaks. However, the presence of stratified soil showed a drastic change in the frequency response with local tips and dips.

Similar conclusions were drawn by Emperador and Domínguez [11], Liingaard et al. [12], Andersen and Liingaard [13] and Andersen et al. [14], who used boundary element and coupled boundary-element/finite-element models to investigate the frequency dependent stiffness of axisymmetric embedded foundations. In addition, Krenk [15] analysed the vertical impedance of a flexible circular foundation on a homogeneous ground, whereas Yong et al. [16] studied a layered soil. Luco and Westmann [17] applied prescribed conditions under a rigid massless surface foundation and zero traction at the remaining free surface of a homogeneous elastic

half-space in order to solve the system as a mixed boundary-value problem for studying the torsional vibrations. For the same degree of freedom, Veletsos and Damodaran Nair [18] investigated the influence of material damping, while closed-form solutions of the impedance were reported by Novak and Sachs [19] and Avilés and Pérez-Rocha [20].

Furthermore, Wong and Luco [21] evaluated the impedance functions for a rigid square foundation on a viscoelastic half-space by solving an integral equation involving the Green's function. For a similar foundation type, Mita and Luco [22] evaluated the impedance functions by means of a hybrid approach. Finally, the coupled horizontal and rocking vibrations of surface foundations were reported by Veletsos and Wei [23] and Ahmad and Rupani [24] as well as Bu and Lin [25].

For laterally and vertically loaded monopiles and jackets, the soil structure interaction is traditionally analysed by means of a nonlinear Winkler foundation approach, in which the pile is continuously supported by nonlinear uncoupled springs and dashpots to represent the horizontal and vertical soil resistance and damping characteristic. Following this approach, El Naggar and Novak [26–29], El Naggar and Bentley [30], Kong et al. [31], Allotey and El Naggar [32], Memarpour et al. [33], Andersen et al. [34] and Damgaard et al. [35] investigated the vibration response and dynamic properties of monopile structures. However, using this approach for fast time domain analysis in aeroelastic codes does not seem obvious, since only the soil-foundation interface is important with regard to the dynamic structural behaviour of the wind turbine.

1.2 Objective

The objective of this work is to evaluate the influence of the multi-layered strata on the magnitude of the soil-structure interaction (SSI) of gravity-based foundations. To reach the proposed objective, a rigid square foundation is attached to a multi-layered soil and subjected to torsional, vertical, rocking and horizontal excitations to study the impedance matrices for different combinations of soil properties in order to show the effect of the multi-layered strata on SSI.

1.3 Methodology

To reach the previous objective, the following methodology is applied.

- To develop dynamic matrix, a general overview of dynamic impedance is carried out.
- Several modelling considerations are taken account, such as structural damping, element size and analytical validation.
- The problem statement and solutions are exposed.

1.4 Organization of this document

This project is organized by chapters, which are dependent between each of them. This way each chapter is connected to the next one. The first chapter will introduce earlier works of different authors on this subject and their conclusions and general overview of dynamic impedance to give basic information.

In the second chapter explains the modelling considerations which will be taken account to provide the required information to proceed with the calculation of foundation impedances using 3D boundary element program "BEASSI" and "SAP2000".

The last chapter introduces the problem statement and the result drawn from "BEASSI" and "SAP2000".

1.5 Software used

The following computer programs were used in this thesis:

- BEASSI, Boundary Element Analysis of Soil Structure Interaction
- SAP2000, Integrated Software for Structural Analysis and Design
- EXCEL, spreadsheet program, Microsoft Inc.

CHAPTER 2

Damping of offshore wind turbines

2.1 Introduction

The development of offshore wind turbines (OWT's) faces new challenges for the support structure, a greater random environmental load demand. These increased offshore wind speeds result in a much greater demand on monopile support structures, as resonance generated by stochastic wind, wave and mechanical loading causes them to fall subject to accelerated cyclic fatigue.

When a structural element is in contact with the ground, the structural displacements and the ground displacements are not independent of each other. The process by which the response of the structure affects the response of the underlying soil and by which the response of the soil affects the response of the structure is known as soil-structure interaction (SSI).

It is well known that the dynamic response of a structure on a flexible soil may be different from the response of a similarly excited structure supported on firm soil. Veletsos and Verbic [36] showed that the presence of flexible soil underneath the foundation of a structure increases the damping capacity of the foundation and reduces the structure's natural frequency. Luco [37], in a study on seismic response of tall chimneys, showed that soil-structure-interaction (SSI) had an effect only for softer soils and could lead to reductions or increases in response, depending on the characteristics of the chimney and the seismic excitation. Luco's work was verified by Moghaddasi et al. [38] who carried out a Monte Carlo simulation for a range of single degree of freedom (SDOF) structures and soil conditions excited by a series of seismic excitations. Novak and Hifnawy [39,40] showed that the response of a structure when subject to dynamic wind loading can be affected by SSI. A full review of the development of SSI can be found in Kausel [41].

Zaaijer [42] modelled the dynamic behaviour of foundations of offshore wind turbines. The author investigated the sensitivity of the support structure's natural frequency to variation in foundation types. This work was extended by Camp et al. [43]. Particular attention was paid to the uncertainty of several key geotechnical design parameters. The report found that the sensitivity of gravity base foundations to soil parameters is higher than for piled foundations, lending to the presumption that gravity base foundations cannot be uniform within a wind farm, but rather designed for local soil conditions at the location of the foundations.

During the operation of an offshore wind turbine the displacement of the subsoil structure causes a cyclic motion of the surrounding soil, leading to a combination of radiation damping and material damping. [44]

- Radiation damping: This damping is also referenced as geometrical damping and is due to the radiation boundary condition at large distances from the foundation. This damping source can be determined by computations in the frequency domain. In linear theory, it only depends on the foundation size, and the soil elastic parameters (elastic or poroelastic behaviour). DNV [45] suggest its evaluation when SSI is relevant for the design. For GBS the main damping contribution comes from this term.
- Material damping: Damping caused by viscoelastic behaviour of the material. This damping is considered in frequency-domain by complex-valued damping rates.

2.2 Dynamic impedance definition

The response of a rigid foundation to static or dynamic load solely from the deformation of the supporting soil. The static soil stiffness ($K = F/U$) is used to model the soil-structure(foundation) response to static load. In an analogous manner, the dynamic soil impedance/stiffness ($K = F(t)/U(t)$) is used to model the soil-structure(foundation) response to dynamic loads. In particular, six dynamic impedances are required, three translational and three rotational, to formulate the dynamic equilibrium equation of a rigid foundation, as shown in Figure 2.1.

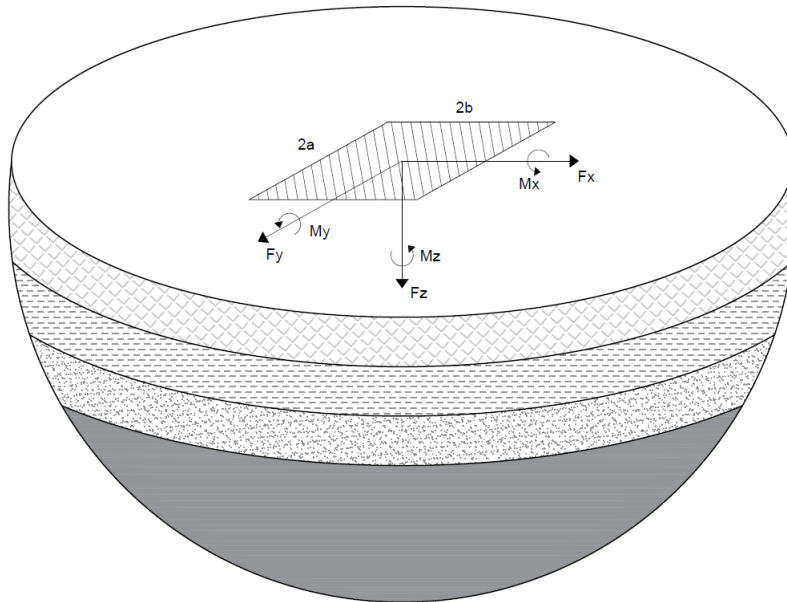


Figure 2.1: Degrees of freedom for rigid surface foundation resting on a layered half-space

The dynamic equilibrium equation that determines the foundation behaviour under dynamic loads has the following expression:

$$M\ddot{u}(t) + C\dot{u}(t) + Ku(t) = F(t) \quad (2.1)$$

where M , C and K are the mass, damping and stiffness matrices respectively, $u(t)$ the vector of nodal displacements and $F(t)$ the vector of external nodal loads.

Using new dynamic variables for natural frequency, ω_n , and damping ratio, ξ , the equation of motion can re-write. Note that

$$\frac{C}{M} = 2\xi\omega_n \quad (2.2)$$

$$\ddot{u}(t) + \left(\frac{C}{M}\right)\dot{u}(t) + \left(\frac{K}{M}\right)u(t) = \frac{F(t)}{M} \quad (2.3)$$

$$\ddot{u}(t) + 2\xi\omega_n\dot{u}(t) + \omega_n^2u(t) = \frac{F(t)}{M} \quad (2.4)$$

From Eq. 2.3 and 2.4, the damping ratio ξ can be obtained

$$\xi = \frac{C}{2M\omega_n} \quad (2.5)$$

Considering harmonic loads ($u(t) = Ue^{i\omega t}$ and $F(t) = Fe^{i\omega t}$). Substituting these statements into the dynamic equilibrium equation given by Eq. 2.1, the following frequency domain equation can be obtained.

$$[K - \omega^2M + i\omega C]Ue^{i\omega t} = Fe^{i\omega t} \quad (2.6)$$

The normalized impedance functions are complex functions of the dimensionless frequency

$$\bar{\omega} = \frac{\omega a}{C_s} \quad (2.7)$$

The procedure used to calculate the dynamic impedances of a rigid surface foundation can be summarized in the following steps:

1. The foundation is modelled as massless and rigid; therefore, only the geometry of the area in contact with the soil is required (e.g., 2a and 2b shown in Figure 2.1). The use of a massless foundation is important since it avoids the need for recalculating the dynamic impedance every time that the foundation mass changes, which often happens during the design process.
2. A harmonic force or moment of frequency ω and of unit magnitude is applied to the rigid foundation (e.g., $F(t) = Fe^{i\omega t}$ or $M(t) = Me^{i\omega t}$), as shown in Figure 2.2. Such force/moment generates stress waves that propagate into the underlying soil, which is modelled as a viscoelastic material. Therefore, the following properties are required for each soil layer: thickness (h), Young's modulus (E), Poisson's ratio (ν), density (ρ), and material damping (ξ).

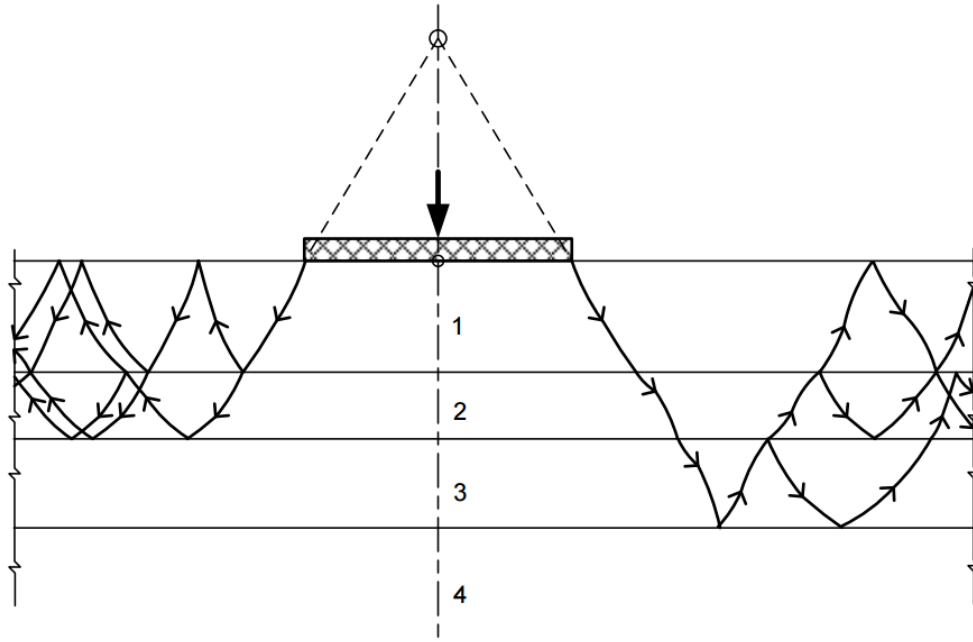


Figure 2.2: Downwards and upwards wave propagation for surface disk in layered half-space, according to Ref [1]

3. The steady state vibration amplitude ($U(t) = Ue^{i\omega t}$) of the foundation under the harmonic force is obtained by keeping track of the reflections and refractions that take place every time that the stress waves reach a soil layer boundary. This is achieved by finding the different wave paths shown in Figure 2.2.
4. The dynamic impedance $K(\omega)$ is defined as the ratio between the harmonic force acting on the foundation and its vibration amplitude as shown in Eq. 2.8. It must be noted that this is a frequency dependent complex quantity.

$$K(\omega) = \frac{F(t)}{U(t)} \quad (2.8)$$

5. In soil dynamics, it is customary to express the complex dynamic impedance as shown in Eq. 2.9. In addition, the real and imaginary parts of the dynamic impedance are associated, by analogy, with a dynamic (frequency dependent) stiffness and damping as shown in Eq. 2.10.

$$K(\omega) = \bar{k} + i\omega C \quad (2.9)$$

$$\begin{aligned} \bar{k}(\omega) &= \text{Re}(K(\omega)) \\ C(\omega) &= \frac{\text{Im}(K(\omega))}{\omega} \end{aligned} \quad (2.10)$$

The real parts of the impedance functions are generally thought of as dynamic stiffness coefficients $Re(K(\omega)) = K - \omega^2 M$ while the imaginary parts divided by frequency are thought of as damping coefficients $Im(K(\omega)) = i\omega C$.

The DNV document [45] provide simple formulation to evaluate the stiffness and damping coefficient of the main solid-rigid modes of the GBS foundation. Figure 2.3 shows the formulation to estimate the parameters for circular foundation.

Table 7.1 Spring and damping coefficients, mass and damping ratios and «effective mass» for a rigid circular foundation resting on an elastic half space.			
<i>Mode of vibration</i>	<i>Spring coefficient k</i>	<i>Damping coefficient c</i>	<i>«Effective mass»</i>
Vertical (z)	$\frac{4 Gr_o}{1 - \nu}$	$\frac{3.4 r_o^2}{1 - \nu} \sqrt{\rho G}$	$\frac{1.08 \rho r_o^3}{1 - \nu}$
Horizontal (x)	$\frac{8}{2 - \nu} Gr_o$	$\frac{4.6}{2 - \nu} r_o^2 \sqrt{\rho G}$	$\frac{0.76 \rho r_o^3}{2 - \nu}$
Rocking (ψ)	$\frac{8 Gr_o^3}{3 (1 - \nu)}$	$\frac{0.8 r_o^4 \sqrt{\rho G}}{(1 - \nu) (1 + B_\psi)}$	$\frac{0.64 \rho r_o^5}{1 - \nu}$
Torsion (θ)	$\frac{16 Gr_o^3}{3}$	$\frac{4 r_o^4 \sqrt{B_\theta \rho G}}{1 + 2 B_\theta}$	$0.24 \rho r_o^5$
r_o = radius of foundation (rectangular foundations are treated as described in Section G5.2.2.4). G, ν and ρ = shear modulus, Poisson's ratio and mass density of the elastic halfspace.			

Figure 2.3: Stiffness and damping for circular foundations

CHAPTER 3

Modelling Considerations

The boundary element method is used to determine the dynamic stiffness of rectangular foundations resting upon within a viscoelastic multi-layered half-space to capture three dimensional effects, the soil layer profile, and the geometry of the foundation. Due to the characteristics of the soil and the excitation periods (from 0.5 to 10 seconds) the saturated half space is modelled with three-dimensional elasticity equations, in which the Poisson's ratio is taken close to 0.5 (0.45 in computations) to represent low compressibility conditions and saturated density as the material density at each layer. The purpose of this section is to provide the required information to proceed the calculation of foundation impedances using 3D boundary element program "BEASSI" and "SAP2000".

3.1 Structural damping

It is called structural damping when internal friction of a material transforms vibrational energy into heat. The structural damping is considered in modal analysis through the damping rate ξ which relates the damping constant C of the system respect to the critical damping rate.

According to the experimental works (J. Taillon et al. [46]), reveals that for a lattice tower with structural steel, damping rate is non-linear, and it depends on the loads, connections (welded, bolted), etc. Figure 3.1 shows the dependence on the loading level and the damping rate.

The relation between the level of load and damping is also recognized in codes by providing different values, depending on the type of loading. ASCE [47] recommends, in its commentary, to use a value between 0.15% and 0.5% for wind effect on steel towers, and 5% for earthquake. ASCE [48] commentaries recognize that damping can be influenced by the level of structural response. For elastic dynamic analysis, AASHTO [49] recommends a damping ratio of 1% for bolted and welded structures. The Canadian Bridge Standard [50] recommends the use of damping ratio of 0.75% to 1% for wind analysis of sign structures and vibration of pedestrian bridges. The code AISC [51] proposes values of 3% to 5% for a steel structure under earthquake loading. The Eurocode 1 part 1-4 [52] defining the wind action provides values of structural damping of 0.32% for welded lattice steel towers, 0.48% when high strength bolts are used and 0.80% in the case of ordinary bolts. In the Eurocode 8 part 1-1 [53] for seismic design a damping value of 2% for welded structures and 4% for bolted structures is recommended. Overall, there is no general agreement on the value of damping that shall be used in structural

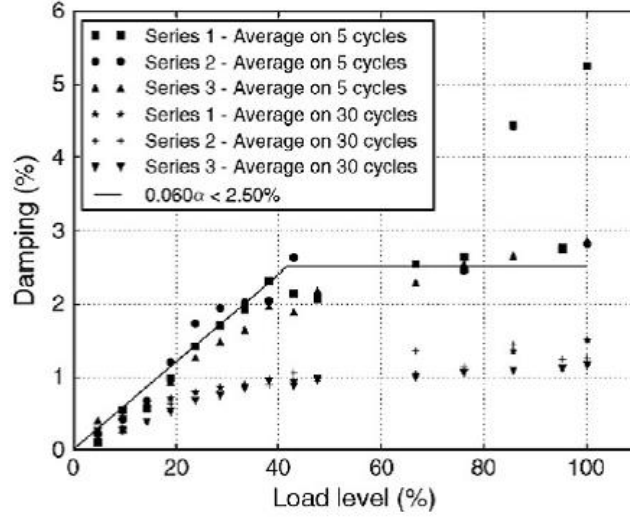


Figure 3.1: Damping ratio average in terms of the % load level.

design according to the level of stress and there is no guidance on the modelling assumption to be used. This is probably due to the lack of full scale damping and stiffness measurements for lattice towers as observed by Glanville et al. [48].

Experience [54] shows that the structural damping in terms of the logarithmic decrement is usually of the order of 3% ($\xi \approx 0.48\%$) for the blades and of 5% ($\xi \approx 0.8\%$) for the shaft and the tower. Taking to account all matters mentioned above, 0.5% is adapted for the structural damping in the simulations.

3.2 Element size

The running time and accuracy of a boundary element solution are greatly affected by the mesh quality. The major advantage of this method is that only the boundary surface (e.g., the exterior of the vibrating body) needs to be modelled with a mesh of elements. Several recommendations are provided in order to set the element size for wave propagation analyses. The general concept is that the mesh should be fine enough to resolve the propagating wave. Of course, better results should be expected from highly refined models; nevertheless, they are computationally expensive and may be impractical from an engineering point of view. Therefore, a compromise must be reached among discretization quality and solution efficiency.

The dimensions of the square foundation are assumed to be $2a \times 2b$ (width x length). Each layer is characterized by thickness $h(m)$, the shear wave velocity $V_s(m/s)$, Poisson's ratio ν , density $\rho_s(kN/m^3)$, complex shear modulus $G(MPa)$ and Young's modulus $E(MPa)$.

In order to save some computational cost, mesh sensitivity test will be performed. The geometry of the system considered is massless rigid surface foundation of a base area $2a \times 2b$ in a uniform elastic half-space. The considered data's which are dimensionless, $h = 10$, $G = 1$, $\nu = 0.3$, $\rho = 1$ and the results are shown in figure 3.2 using "BEASSI".

Taking to account the result, the mesh size is taken as 11×11 , which represents 121 elements and 144 nodes.

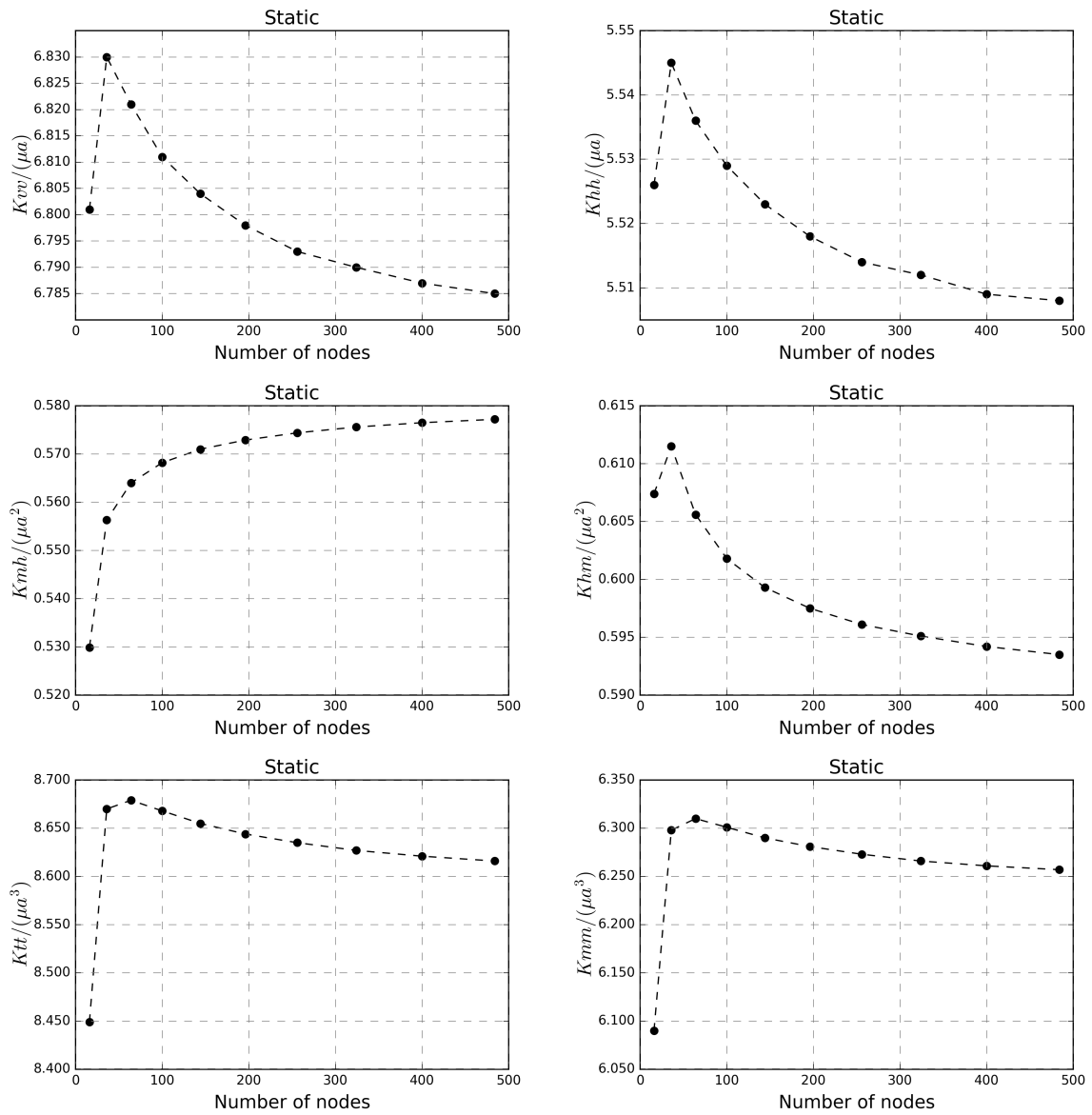


Figure 3.2: Mesh dependency

3.3 Analytical validation

An analytical validation is carried out, comparing the simple formulation provided by DNV document [45] in figure 2.3 with the results from "Beassi", choosing the finest mesh size 21 x 21. Considering the same data's given as in section 3.2, table 3.1 shows the obtained data.

	Static Case	
Mode of vibration	DNV formulation	BEASSI
K_{vv} (kN/m)	6.448	6.785
K_{hh} (kN/m)	5.310	5.508
K_{mm} (kN/rd)	5.473	6.257
K_{tt} (kN/rd)	7.662	8.616

Table 3.1: Comparison between simple formulation provided by DNV from figure 2.3 and "BEASSI"

The result extracted from "BEASSI" has taking into account the mesh of elements, unlike the formulation provided by DNV, and the geometry of foundation marks the difference between the results.

CHAPTER 4

Problem statement

4.1 Introduction

The purpose of this section is to display the steps required for calculating the dynamic impedance of foundation on multi-layered soil. To do this, it is important to describe the geometry and structural properties of the foundation, and to combine such a model with the surrounding soil using the displacement compatibility and equilibrium conditions at the interface. There are two basic models that can be used to represent a foundation:

- a rigid body model, which is appropriate for the case of massive foundations and
- flexible foundation model, which the flexibility of the foundation is taken into account.

In this case, the first model of rigid body model will be used due to the dimension of the foundation. For the case of a rigid model of a three-dimensional foundation, the motion of the foundation can be expressed in terms of six components: one vertical, two horizontal, two rocking and one torsional. The soil profile with rigid square foundation is shown in figure 4.1, in which different combinations of soil properties for the multi-layered strata are used. To obtain it, the Young's modulus E of each layer will be increased 10%, 20% and 30%.

The gravity based foundation used for this project is a concrete caisson with a dimension of 33 x 33m, shown as in figure 4.1.

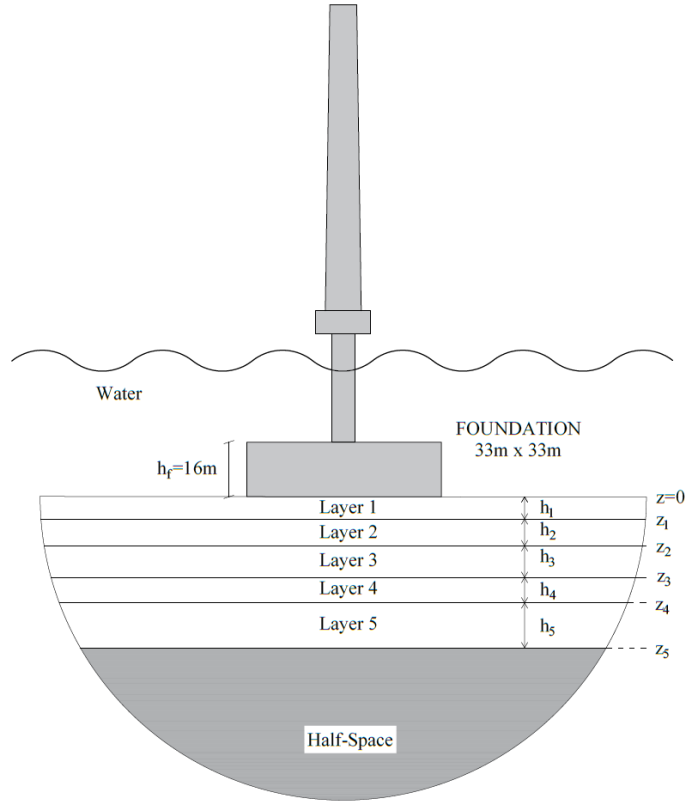


Figure 4.1: A gravity based foundation on a multi-layered soil

Table 4.1 shows the properties of multi-layered soil, it consists of five layers, which is used to analyse and it will be taken as reference strata during the experiment.

Layer	$h(m)$	$z(m)$	$\rho_s(kN/m^3)$	$E(Mpa)$	ν	$G(Mpa)$	$V_s(m/s)$	Material
1	1.5	1.5	22	34.8	0.45	12	73.85	Berm
2	3	4.5	18	17.4	0.45	6	57.74	Surface sediments
3	2	6.5	21	58	0.45	20	97.59	Reworked till
4	3	9.5	22	174	0.45	60	165.14	Over Consolidated till
5	3	12.5	18	43.5	0.45	15	91.29	Lower cretaceous

Table 4.1: Properties of multi-layered soil

With regards to the above mentioned data's, the concrete foundation is designed and analysed in the Boundary Element Analysis for Soil-Structure Interaction "Beassi". The purpose of this analysis is to obtain the dynamic stiffness results for vertical (K_{vv}), horizontal (K_{hh}), rocking (K_{mm}) and torsion (K_{tt}) for different half-space configurations increasing each layers Young's modulus 10%, 20% and 30%. The foundation is fully-contact to the layered half-space through a 1.5 m thickness berm with stone and protection material and is meshed

by 11x11 four noded singular elements. In table 4.2 shows the dynamic stiffness for vertical (K_{vv}), horizontal (K_{hh}), rocking (K_{mm}) and torsion (K_{tt}) which is calculated by "BEASSI", from periods 0.5s to 10s. To simplify the experiment, only excitation period of 2s will be taken into account to run the simulations to compare the results.

T(s)	K_{vv} (kN/m)		K_{hh} (kN/m)		K_{mm} (kN/rd)		K_{tt} (kN/rd)	
	Re	Im	Re	Im	Re	Im	Re	Im
0.5	9.9495E+05	5.8836E+06	1.1920E+06	1.2890E+06	3.3179E+08	3.6764E+08	2.7546E+08	1.8508E+08
1	1.5543E+06	2.5146E+06	1.3355E+06	7.5488E+05	3.7788E+08	1.3390E+08	3.9055E+08	6.3959E+07
1.5	1.7810E+06	1.6117E+06	1.3474E+06	5.3846E+05	4.1669E+08	6.7571E+07	4.2424E+08	3.7033E+07
2	1.8800E+06	1.1989E+06	1.3484E+06	4.2580E+05	4.3960E+08	4.3070E+07	4.3933E+08	2.7761E+07
2.5	1.9315E+06	9.6179E+05	1.3474E+06	3.5670E+05	4.5335E+08	3.2451E+07	4.4715E+08	2.3778E+07
3	1.9622E+06	8.0834E+05	1.3464E+06	3.0967E+05	4.6197E+08	2.7276E+07	4.5173E+08	2.1791E+07
4	1.9949E+06	6.2093E+05	1.3434E+06	2.4978E+05	4.7113E+08	2.2842E+07	4.5658E+08	2.0042E+07
5	2.0107E+06	5.1064E+05	1.3405E+06	2.1285E+05	4.7599E+08	2.1188E+07	4.5901E+08	1.9355E+07
6	2.0206E+06	4.3798E+05	1.3395E+06	1.8790E+05	4.7841E+08	2.0438E+07	4.6035E+08	1.9034E+07
8	2.0305E+06	3.4799E+05	1.3375E+06	1.5593E+05	4.8111E+08	1.9837E+07	4.6197E+08	1.8765E+07
10	2.0354E+06	2.9433E+05	1.3355E+06	1.3632E+05	4.8245E+08	1.9622E+07	4.6251E+08	1.8662E+07

Table 4.2: Dynamic stiffness on five layered strata(reference strata)

4.2 Dynamic stiffness using 3D boundary element program BEASSI

Next sub-chapters presents the variations in the dynamic stiffness considering different values of Young's modulus. This analysis is made in order to show the influence of multi-layered strata on the SSI effect.

4.2.1 Variation of Young's modulus 10%

The proceeding consist in increasing ten percent the Young's modulus of each one of the layers. In other words, the Young's modulus of layer one is increased 10% leaving the rest of the layers without changes and so on till layer five. To get an idea, dynamic stiffness of reference strata is also shown in the table 4.3.

T=2s	K_{vv} (kN/m)		K_{hh} (kN/m)		K_{mm} (kN/rd)		K_{tt} (kN/rd)	
Layers	Re	Im	Re	Im	Re	Im	Re	Im
Ref.	1.8800E+06	1.1989E+06	1.3484E+06	4.2580E+05	4.3960E+08	4.3070E+07	4.3933E+08	2.7761E+07
1	1,8879E+06	1,2078E+06	1,3820E+06	4,4382E+05	4,4499E+08	4,3798E+07	4,5712E+08	2,9190E+07
2	1,8981E+06	1,2251E+06	1,3885E+06	4,4791E+05	4,5154E+08	4,4769E+07	4,5510E+08	2,9014E+07
3	1,8840E+06	1,2058E+06	1,3593E+06	4,2847E+05	4,4283E+08	4,3529E+07	4,4229E+08	2,7896E+07
4	1,8830E+06	1,2078E+06	1,3682E+06	4,2303E+05	4,4283E+08	4,3583E+07	4,4337E+08	2,7546E+07
5	1,8889E+06	1,2098E+06	1,3553E+06	4,2639E+05	4,4337E+08	4,3529E+07	4,4041E+08	2,7734E+07

Table 4.3: Dynamic stiffness after increasing Young's modulus of each layer 10%

4.2.2 Variation of Young's modulus 20%

Table 4.4 shows the results of dynamic stiffness after increasing Young's modulus 20%.

T=2s	K_{vv} (kN/m)		K_{hh} (kN/m)		K_{mm} (kN/rd)		K_{tt} (kN/rd)	
Layers	Re	Im	Re	Im	Re	Im	Re	Im
Ref.	1.8800E+06	1.1989E+06	1.3484E+06	4.2580E+05	4.3960E+08	4.3070E+07	4.3933E+08	2.7761E+07
1	1,8949E+06	1,2167E+06	1,4127E+06	4,6065E+05	4,4957E+08	4,4445E+07	4,7383E+08	3,0564E+07
2	1,9127E+06	1,2486E+06	1,4256E+06	4,6843E+05	4,6251E+08	4,6348E+07	4,6995E+08	3,0173E+07
3	1,8879E+06	1,2118E+06	1,3692E+06	4,3055E+05	4,4580E+08	4,3933E+07	4,4526E+08	2,7977E+07
4	1,8860E+06	1,2167E+06	1,3860E+06	4,2006E+05	4,4580E+08	4,4068E+07	4,4688E+08	2,7330E+07
5	1,8968E+06	1,2197E+06	1,3613E+06	4,2669E+05	4,4661E+08	4,3960E+07	4,4149E+08	2,7707E+07

Table 4.4: Dynamic stiffness after increasing Young's modulus of each layer 20%

4.2.3 Variation of Young's modulus 30%

Table 4.5 shows the results of dynamic stiffness after increasing Young's modulus 30%.

T=2s	K_{vv} (kN/m)		K_{hh} (kN/m)		K_{mm} (kN/rd)		K_{tt} (kN/rd)	
Layers	Re	Im	Re	Im	Re	Im	Re	Im
Ref.	1.8800E+06	1.1989E+06	1.3484E+06	4.2580E+05	4.3960E+08	4.3070E+07	4.3933E+08	2.7761E+07
1	1,9008E+06	1,2246E+06	1,4414E+06	4,7669E+05	4,5388E+08	4,5065E+07	4,9000E+08	3,1885E+07
2	1,9254E+06	1,2689E+06	1,4582E+06	4,8700E+05	4,7197E+08	4,7758E+07	4,8353E+08	3,1251E+07
3	1,8909E+06	1,2167E+06	1,3781E+06	4,3233E+05	4,4822E+08	4,4283E+07	4,4769E+08	2,8031E+07
4	1,8879E+06	1,2246E+06	1,4028E+06	4,1709E+05	4,4849E+08	4,4499E+07	4,5038E+08	2,7114E+07
5	1,9028E+06	1,2286E+06	1,3672E+06	4,2689E+05	4,4984E+08	4,4364E+07	4,4256E+08	2,7654E+07

Table 4.5: Dynamic stiffness after increasing Young's modulus of each layer 30%

Attending to the results, the layer two is found to play a significant role related to the dynamic stiffness. The magnitude of the stiffness functions tend to increase when the mean Young's modulus of the soil profile increases, with the exception of the vertical mode, for which normalized impedance functions are largely independent of the soil profile.

4.3 Coupled model

A fully-coupled model of the system in which the lattice tower, the deck, the mono-pile and concrete caisson foundation has been developed as shown in figure 4.2. The data's of the model is based on two real projects, Moray Firth and Inch Cape Mast for EDP and REPSOL, and was provided by my advisor.

The Figure 4.3 shows the general configuration and the links used in "SAP2000" to connect the rigid body mass (with mass and rotational inertial properties, considering concrete and water fractions), and the soil (modelled by springs and dampers). The foundation is analysed when placed at an embedment depth of 1.5m. With dimensionless quantities K_{vv} , K_{hh} , K_{mm} and K_{tt} obtained from the "BEASSI", after passing it to dimensional quantities, it is possible to run simulations to show the effect of SSI on the wind turbine system with "SAP2000".

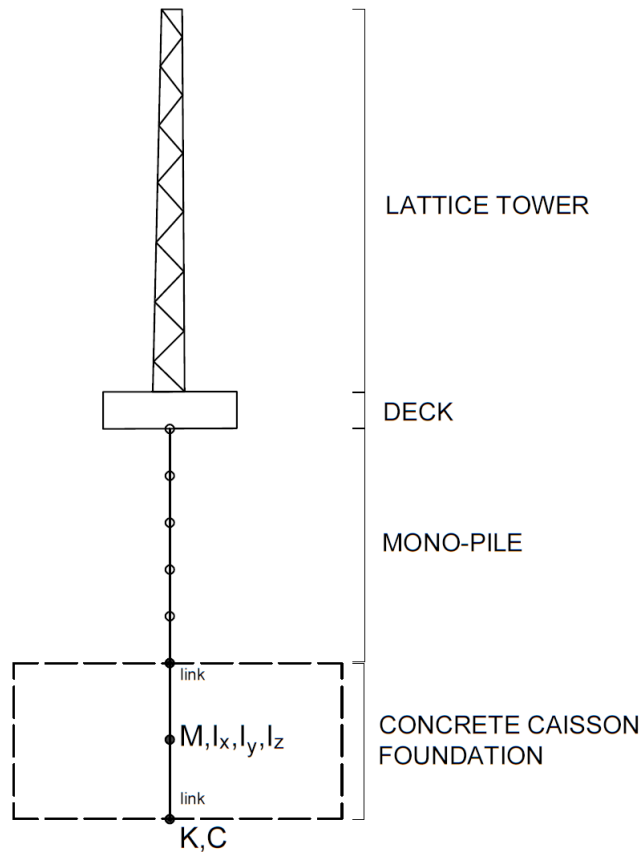


Figure 4.2: Schematic model of an offshore wind turbine for SAP2000

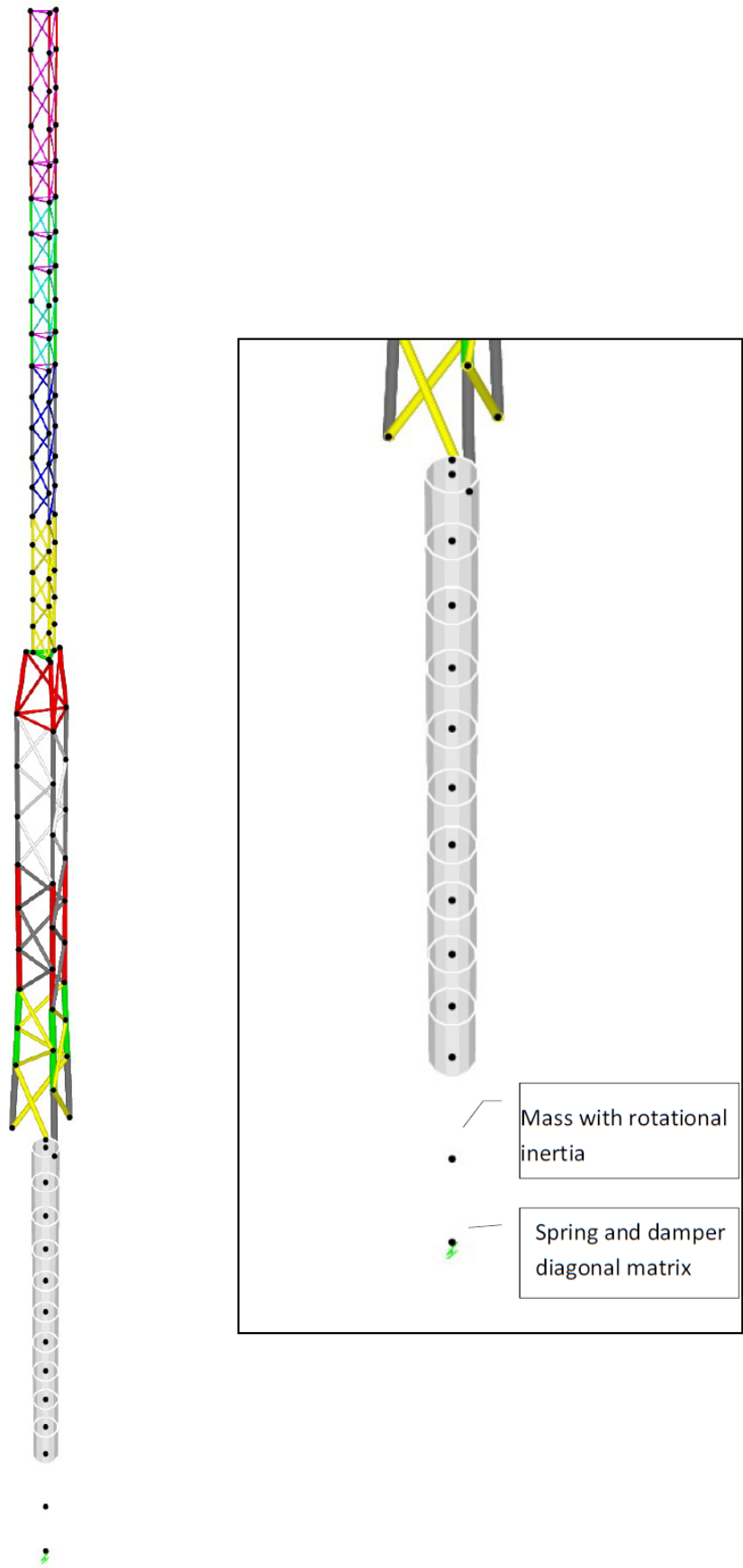


Figure 4.3: Coupled model SAP2000
20

Parameter	Value
Mass of the rigid foundation (<i>Ton</i>)	22941
Mass inertia moment X (<i>Ton · m⁴</i>)	2742311
Mass inertia moment Y (<i>Ton · m⁴</i>)	2574724
Mass inertia moment Z (<i>Ton · m⁴</i>)	4195514

Table 4.6: Mass parameters for SSI

To test the effects of damping in the structure, a free vibration test is carried out. A horizontal force of 20kN is given in X-direction at the top, and it is released, causing free vibration at the structure.

The damper at the foundation is considered with different damping rates at each mode. The rocky rotation at each mode defines the additional damping rate passed to each mode. "SAP2000" computes each modal damping rate. For each mode, 0.5% damping rate is considered, as structural damping.

Figures 4.4 and 4.5 is the result of SSI effect without bringing any modification to the multi-layered soil, and figures from 4.6-4.35, shows the results when the SSI effect is included increasing Young's modulus, G of each layer 10%, 20% and 30%.

In displacements, according to the results below, produces low reductions. This is due to the fact that displacements are affected by the first modes. On the contrary, for accelerations produces great reductions with stronger action on the higher modes.

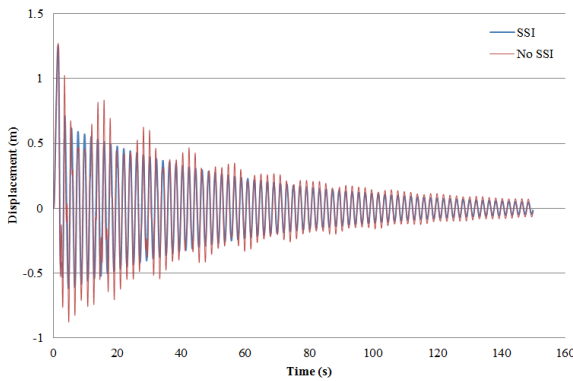


Figure 4.4: Reference Displacement

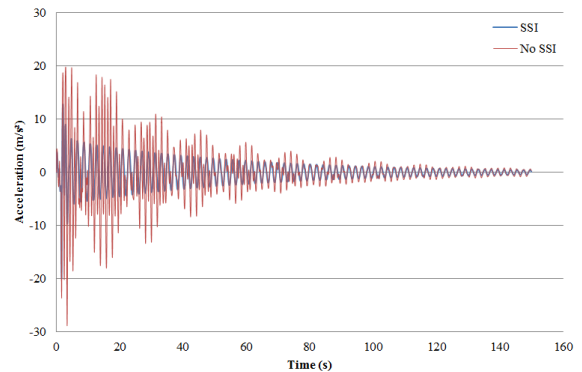


Figure 4.5: Reference Acceleration

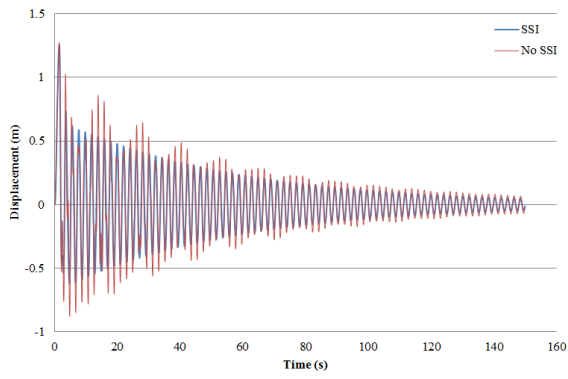


Figure 4.6: Displacement layer 1-10%

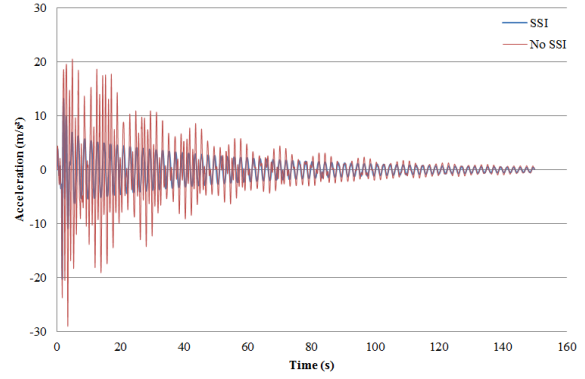


Figure 4.7: Acceleration Layer 1-10%

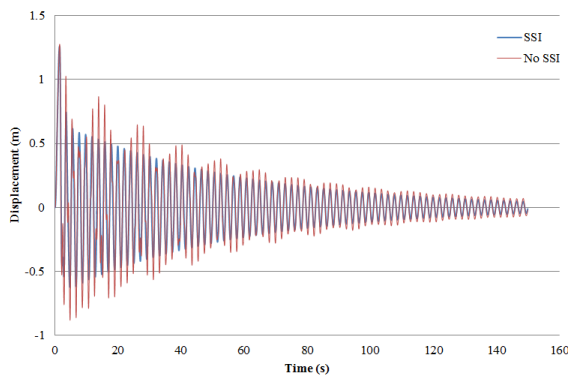


Figure 4.8: Displacement layer 2-10%

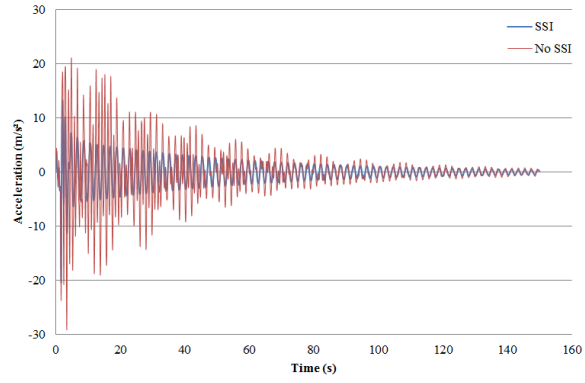


Figure 4.9: Acceleration Layer 2-10%

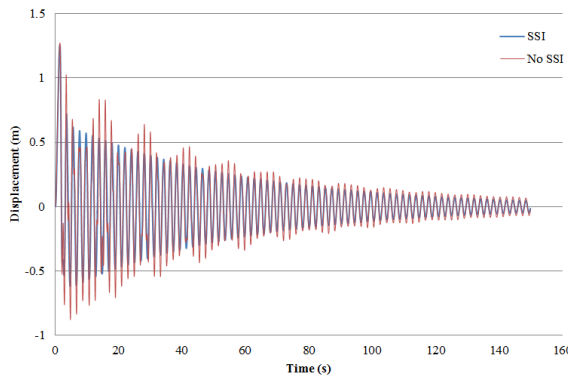


Figure 4.10: Displacement layer 3-10%

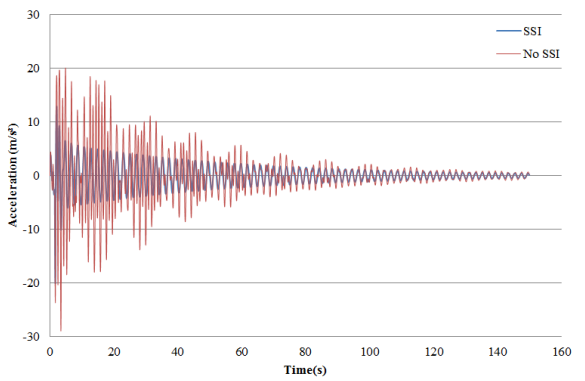


Figure 4.11: Acceleration Layer 3-10%

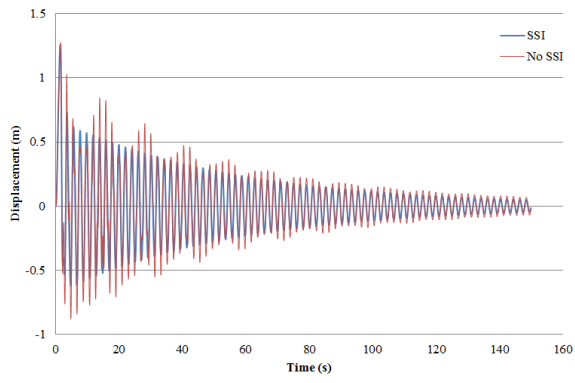


Figure 4.12: Displacement layer 4-10%

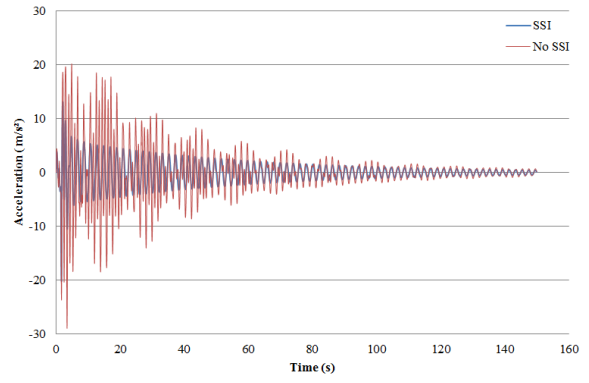


Figure 4.13: Acceleration Layer 4-10%

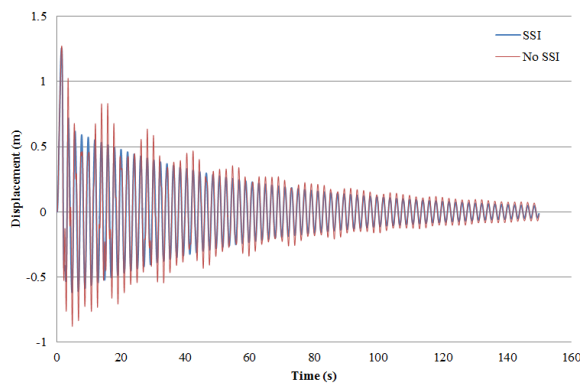


Figure 4.14: Displacement layer 5-10%

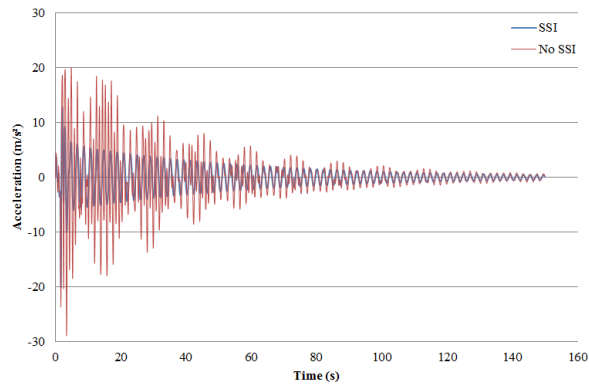


Figure 4.15: Acceleration Layer 5-10%

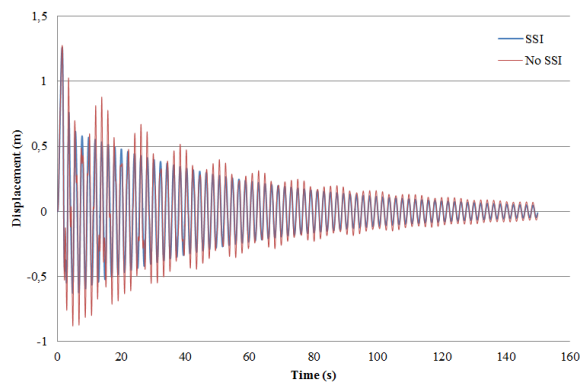


Figure 4.16: Displacement layer 1-20%

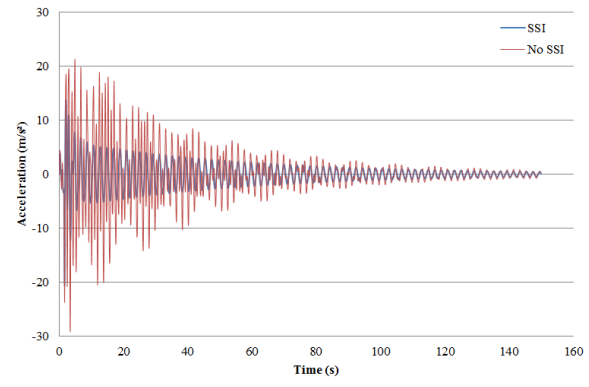


Figure 4.17: Acceleration Layer 1-20%

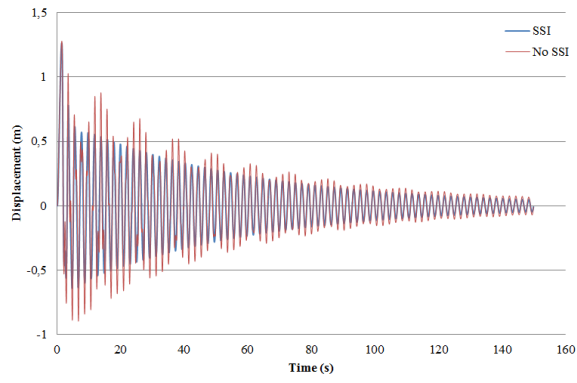


Figure 4.18: Displacement layer 2-20%

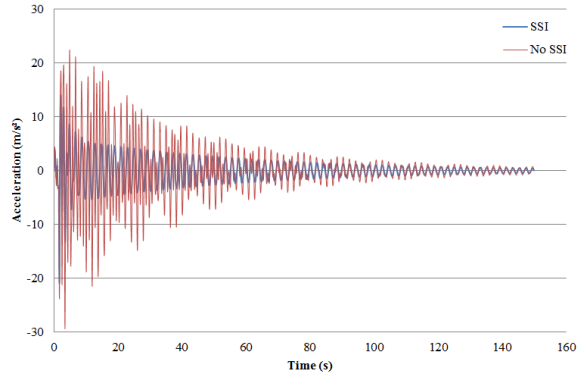


Figure 4.19: Acceleration Layer 2-20%

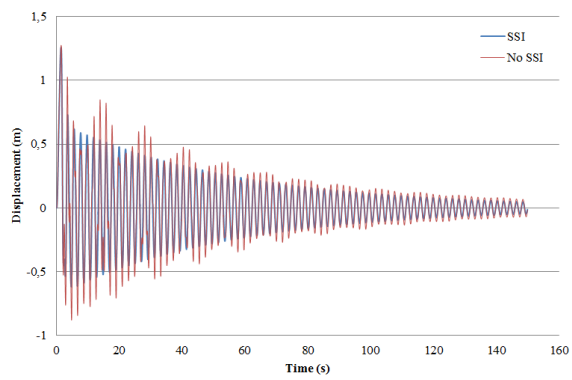


Figure 4.20: Displacement layer 3-20%

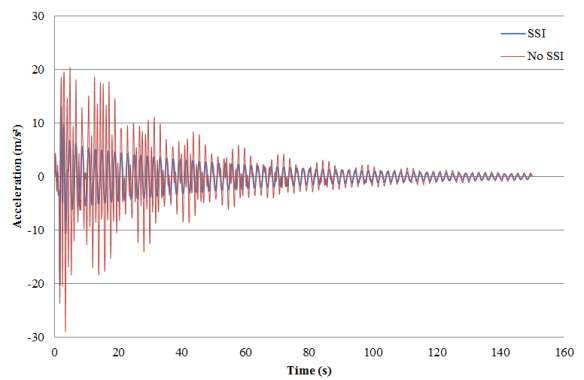


Figure 4.21: Acceleration Layer 3-20%

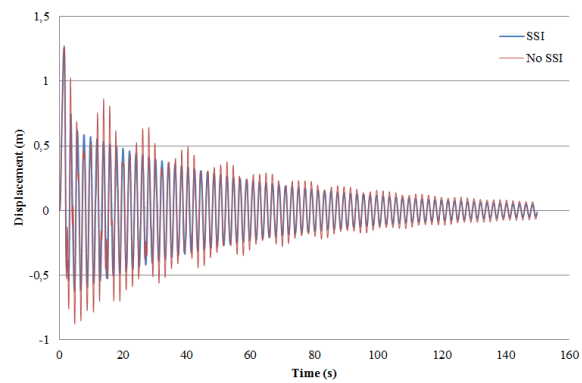


Figure 4.22: Displacement layer 4-20%

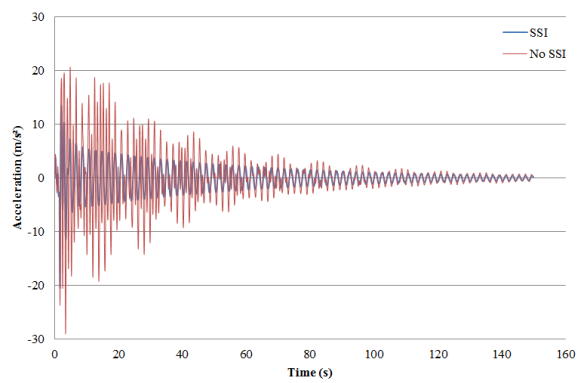


Figure 4.23: Acceleration Layer 4-20%

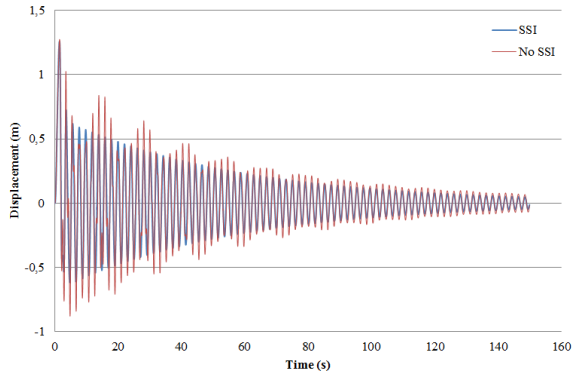


Figure 4.24: Displacement layer 5-20%

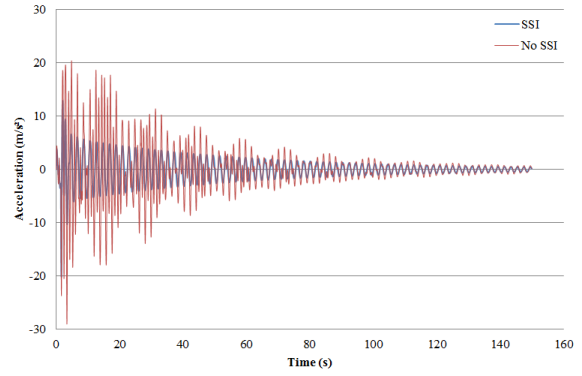


Figure 4.25: Acceleration Layer 5-20%

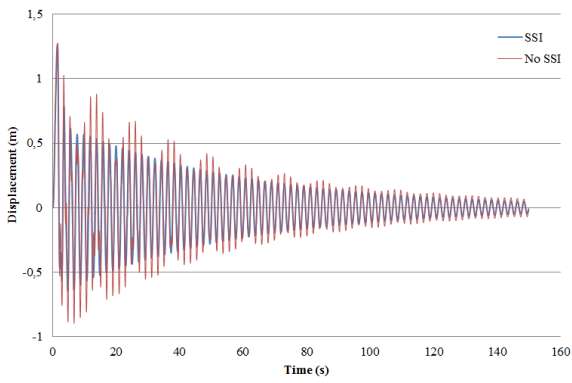


Figure 4.26: Displacement layer 1-30%

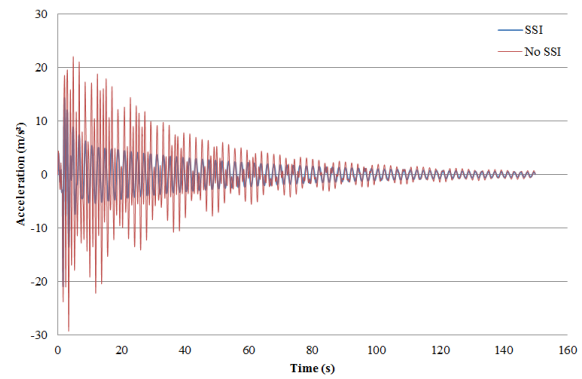


Figure 4.27: Acceleration Layer 1-30%

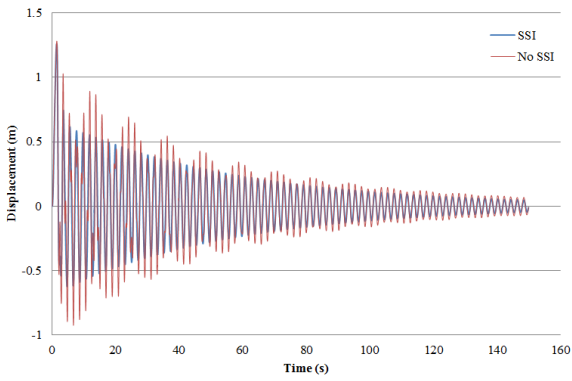


Figure 4.28: Displacement layer 2-30%

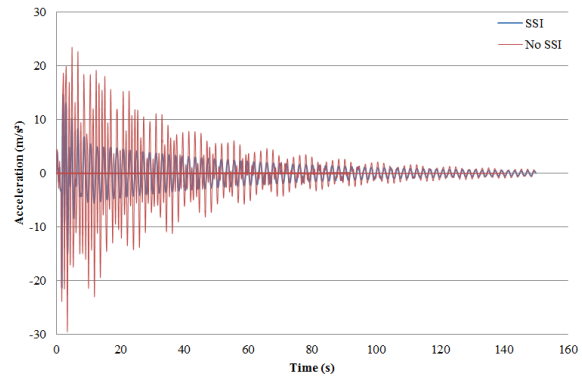


Figure 4.29: Acceleration Layer 2-30%

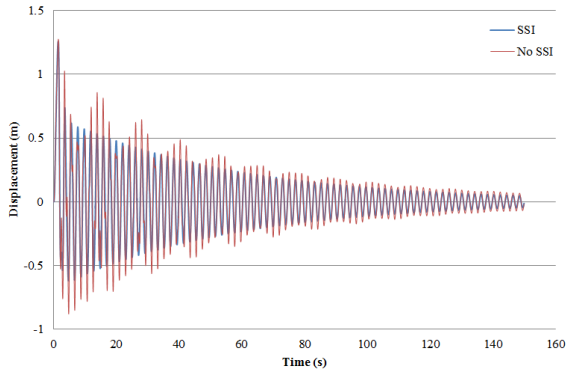


Figure 4.30: Displacement layer 3-30%

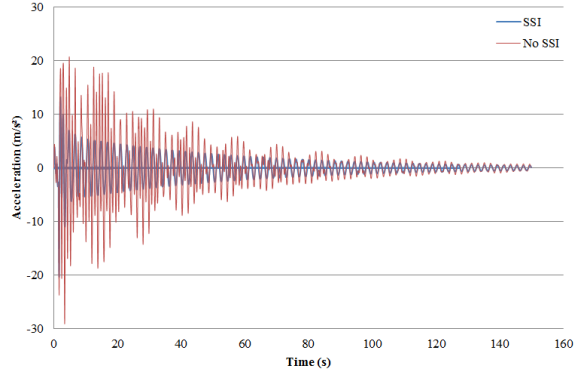


Figure 4.31: Acceleration Layer 3-30%

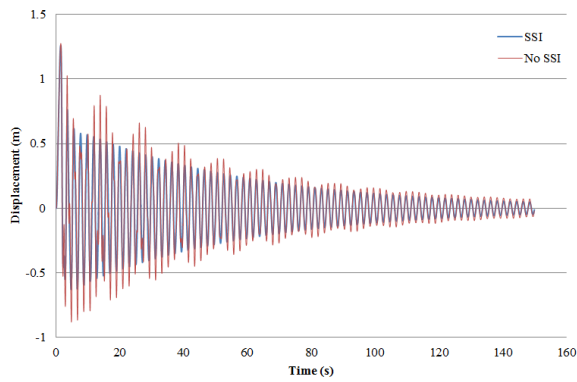


Figure 4.32: Displacement layer 4-30%

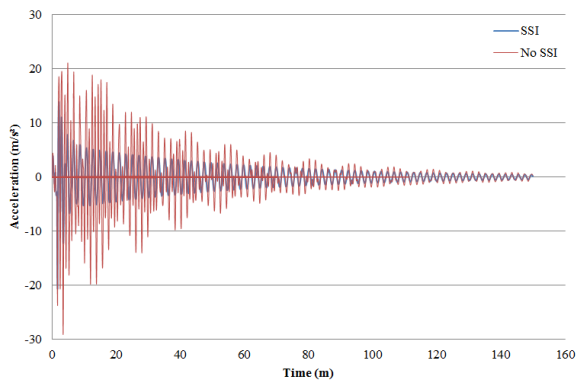


Figure 4.33: Acceleration Layer 4-30%

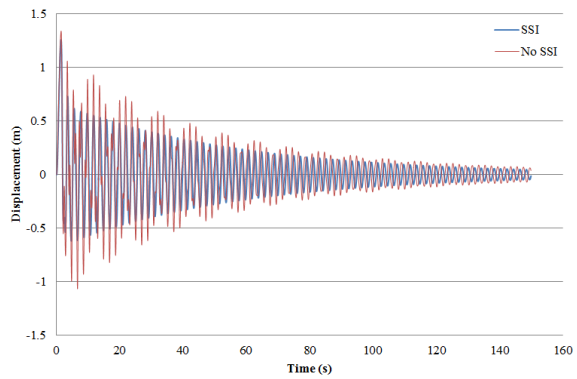


Figure 4.34: Displacement layer 5-30%

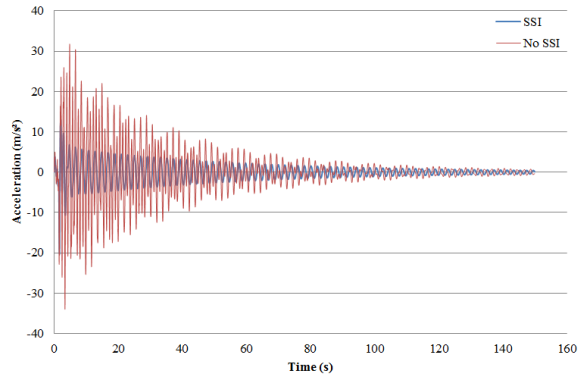


Figure 4.35: Acceleration Layer 5-30%

Figure 4.36 represents the results from "SAP2000". The obtained results confirm the necessity of considering the SSI effects for an accurate estimation of both the fundamental frequency and equivalent damping of the soil-structure system.

10%																							
Ref.				Layer 1				Layer 2				Layer 3				Layer 4				Layer 5			
MODE	PERIOD	DAMP-RATIO	SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %
1	2.041787	0.005863	0.086	2.041589	0.005850	0.085	-1.51	2.041395	0.005842	0.084	-2.43	2.041679	0.005855	0.086	-0.93	2.041668	0.005849	0.085	-1.62	2.041667	0.005854	0.085	-1.04
2	2.041740	0.005857	0.086	2.041544	0.005845	0.085	-1.40	2.041350	0.005837	0.084	-2.33	2.041632	0.005850	0.085	-0.82	2.041622	0.005844	0.084	-1.52	2.041621	0.005849	0.085	-0.93
3	0.948859	0.114823	10.982	0.945122	0.095705	9.071	-17.41	0.943869	0.089880	8.488	-22.71	0.947351	0.106978	10.198	-7.14	0.946545	0.100629	9.563	-12.92	0.947657	0.108710	10.371	-5.57
4	0.947850	0.111114	10.611	0.944263	0.092148	8.715	-17.87	0.943080	0.086495	8.150	-23.20	0.946406	0.103326	9.833	-7.34	0.945627	0.097060	9.206	-13.24	0.946703	0.105064	10.006	-5.70
5	0.890297	0.179147	17.415	0.884339	0.204842	19.984	14.75	0.882342	0.213841	20.884	19.92	0.888234	0.187657	18.266	4.89	0.886841	0.189297	18.430	5.83	0.888786	0.185442	18.044	3.61
6	0.889301	0.185525	18.053	0.883164	0.211215	20.622	14.23	0.881143	0.220016	21.502	19.11	0.887180	0.193985	18.899	4.69	0.885738	0.195509	19.051	5.53	0.887754	0.191736	18.674	3.44
7	0.697327	0.919464	91.446	0.695866	0.924315	91.932	0.53	0.693994	0.935006	93.001	1.70	0.696586	0.923758	91.876	0.47	0.696771	0.925511	92.051	0.66	0.695682	0.925578	92.058	0.67
8	0.614028	0.107910	10.291	0.601962	0.111079	10.608	3.08	0.603296	0.110672	10.567	2.68	0.611970	0.108063	10.306	0.15	0.611224	0.106645	10.165	-1.23	0.613275	0.107684	10.268	-0.22
9	0.456999	0.230381	22.538	0.454762	0.219784	21.478	-4.70	0.453211	0.207343	20.234	-10.22	0.455907	0.223705	21.871	-2.96	0.455644	0.220648	21.565	-4.32	0.455900	0.222728	21.773	-3.40
10	0.450426	0.167919	16.292	0.448884	0.154707	14.971	-8.11	0.447853	0.142495	13.750	-15.61	0.449668	0.160249	15.525	-4.71	0.449486	0.157454	15.245	-6.42	0.449665	0.159502	15.450	-5.17

20%																							
Ref.				Layer 1				Layer 2				Layer 3				Layer 4				Layer 5			
MODE	PERIOD	DAMP-RATIO	SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %
1	2.041787	0.005863	0.086	2.041424	0.005840	0.084	-2.67	2.041055	0.005824	0.082	-4.52	2.041580	0.005848	0.085	-1.74	2.041562	0.005837	0.084	-3.01	2.041566	0.005847	0.085	-1.85
2	2.041740	0.005857	0.086	2.041380	0.005835	0.084	-2.57	2.041013	0.005819	0.082	-4.43	2.041535	0.005843	0.084	-1.63	2.041516	0.005832	0.083	-2.92	2.041521	0.005842	0.084	-1.75
3	0.948859	0.114823	10.982	0.942432	0.080847	7.585	-30.94	0.940450	0.071147	6.615	-39.77	0.946080	0.100077	9.508	-13.43	0.944713	0.089097	8.410	-23.42	0.946675	0.103538	9.854	-10.28
4	0.947850	0.111114	10.611	0.941692	0.077622	7.262	-31.56	0.939824	0.068336	6.334	-40.31	0.945190	0.096518	9.152	-13.76	0.943872	0.085738	8.074	-23.91	0.945767	0.099968	9.497	-10.50
5	0.890297	0.179147	17.415	0.878554	0.225682	22.068	26.72	0.874282	0.241443	23.644	35.77	0.886290	0.194949	18.995	9.07	0.883573	0.197053	19.205	10.28	0.887440	0.190637	18.564	6.60
6	0.889301	0.185525	18.053	0.877233	0.231863	22.686	25.67	0.872934	0.247154	24.215	34.14	0.885184	0.201187	19.619	8.68	0.882378	0.203025	19.803	9.69	0.886378	0.196835	19.184	6.27
7	0.697327	0.919464	91.446	0.694580	0.929394	92.439	1.09	0.691340	0.949195	94.420	3.25	0.695866	0.927352	92.235	0.86	0.696216	0.931573	92.657	1.32	0.694232	0.931197	92.620	1.28
8	0.614028	0.107910	10.291	0.591252	0.114099	10.910	6.01	0.593688	0.113145	10.815	5.09	0.609926	0.108016	10.302	0.10	0.608819	0.105452	10.045	-2.39	0.612524	0.107458	10.246	-0.44
9	0.456999	0.230381	22.538	0.452966	0.209350	20.435	-9.33	0.450310	0.182976	17.798	-21.03	0.454949	0.217147	21.215	-5.87	0.454473	0.211359	20.636	-8.44	0.454995	0.215932	21.093	-6.41
10	0.450426	0.167919	16.292	0.447683	0.143476	13.848	-15.00	0.445979	0.121203	11.620	-28.67	0.449014	0.153222	14.822	-9.02	0.448689	0.148117	14.312	-12.15	0.449048	0.152424	14.742	-9.51

30%																							
Ref.				Layer 1				Layer 2				Layer 3				Layer 4				Layer 5			
MODE	PERIOD	DAMP-RATIO	SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %	PERIOD	DAMP-RATIO	SSI %	Variation SSI %
1	2.041787	0.005863	0.086	2.041274	0.005831	0.083	-3.71	2.040776	0.005809	0.081	-6.26	2.041501	0.005842	0.084	-2.43	2.041466	0.005826	0.083	-4.29	2.041467	0.005839	0.084	-2.78
2	2.041740	0.005857	0.086	2.041230	0.005826	0.083	-3.62	2.040735	0.005805	0.081	-6.07	2.041456	0.005837	0.084	-2.33	2.041421	0.005821	0.082	-4.20	2.041422	0.005835	0.084	-2.57
3	0.948859	0.114823	10.982	0.940384	0.069210	6.421	-41.53	0.938165	0.058411	5.341	-51.37	0.945047	0.094281	8.928	-18.70	0.943194	0.079425	7.443	-32.23	0.945754	0.098576	9.358	-14.79
4	0.947850	0.111114	10.611	0.939740	0.066362	6.136	-42.17	0.937651	0.056117	5.112	-51.83	0.944202	0.090824	8.582	-19.12	0.942421	0.076306	7.131	-32.80	0.944890	0.095098	9.010	-15.09
5	0.890297	0.179147	17.415	0.872911	0.242933	23.793	36.63	0.866877	0.262087	25.709	47.63	0.884526	0.201003	19.600	12.55	0.880392	0.203090	19.809	13.75	0.886080	0.195562	19.056	9.43
6	0.889301	0.185525	18.053	0.871469	0.248869	24.387	35.09	0.865430	0.267382	26.238	45.34	0.883376	0.207141	20.214	11.97	0.879117	0.208795	20.380	12.89	0.884989	0.201647	19.665	8.93
7	0.697327	0.919464	91.446	0.693501	0.933963	92.896	1.59	0.689057	0.961348	95.635	4.58	0.695314	0.930371	92.537	1.19	0.695866	0.937132	93.213	1.93	0.693136	0.936476	93.148	1.86
8	0.614028	0.107910	10.291	0.581415	0.116915	11.192	8.75	0.585292	0.115425	11.043	7.30	0.608268	0.107935	10.294	0.02	0.606449	0.104272	9.927	-3.54	0.611783	0.107136	10.214	-0.75
9	0.456999	0.230381	22.538	0.451423	0.198571	19.357	-14.11	0.448223	0.161471	15.647	-30.57	0.454176	0.211544	20.654	-8.36	0.453447	0.202501	19.750	-12.37	0.454132	0.208928	20.393	-9.52
10	0.450426	0.167919	16.292	0.446675	0.133299	12.830	-21.25	0.444667	0.105306	10.031	-38.43	0.448494	0.147499	14.250	-12.53	0.448002	0.139742	13.474	-17.30	0.448469	0.145513	14.051	-13.75

Figure 4.36: Values of SSI obtained from SAP2000

The figures 4.37 - 4.39 shows the damping percentage by SSI effect in each mode calculated by using SAP2000. The peaks on mode 7 is more than 90%, almost all the damping is produced by SSI, contrary to what happens to the rest of the modes, almost 30% is by SSI effect.

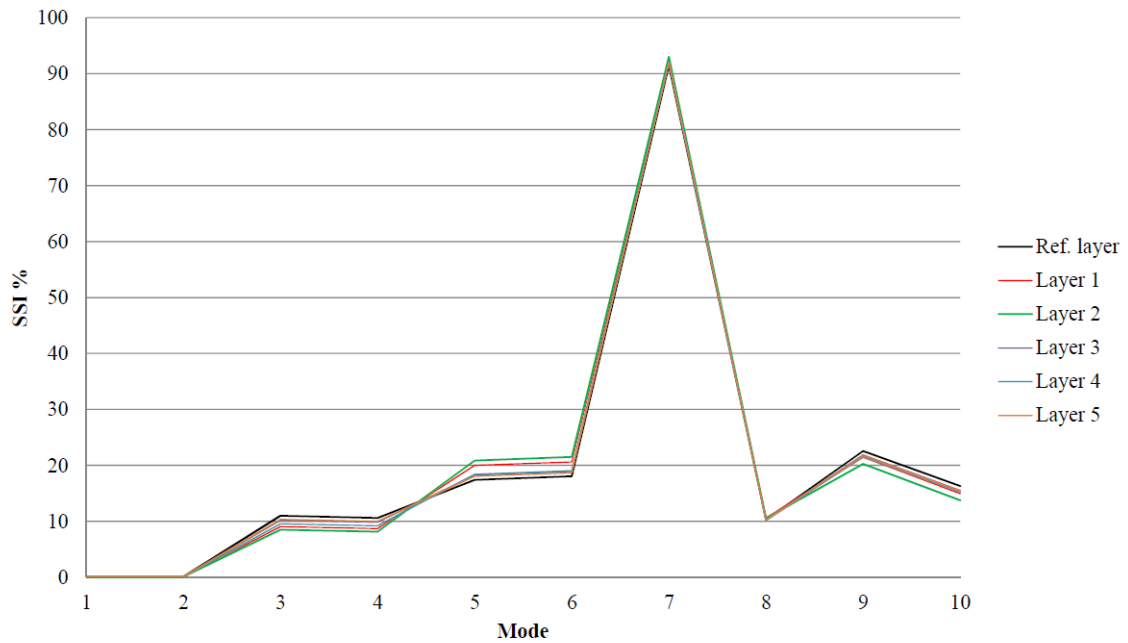


Figure 4.37: SSI-10%

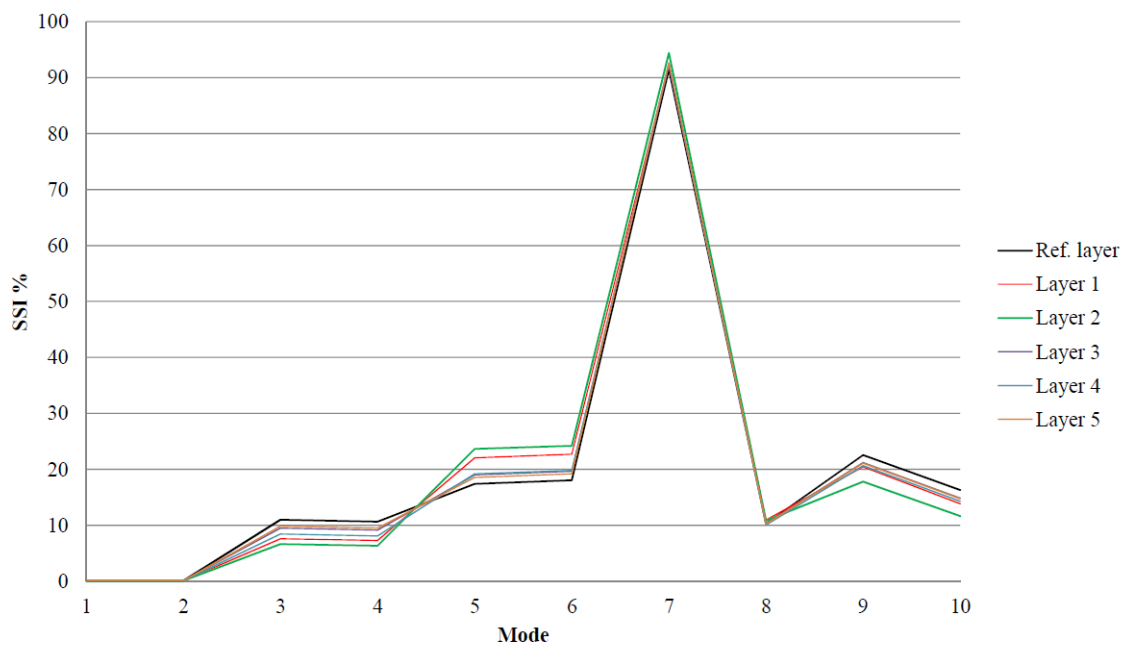


Figure 4.38: SSI-20%

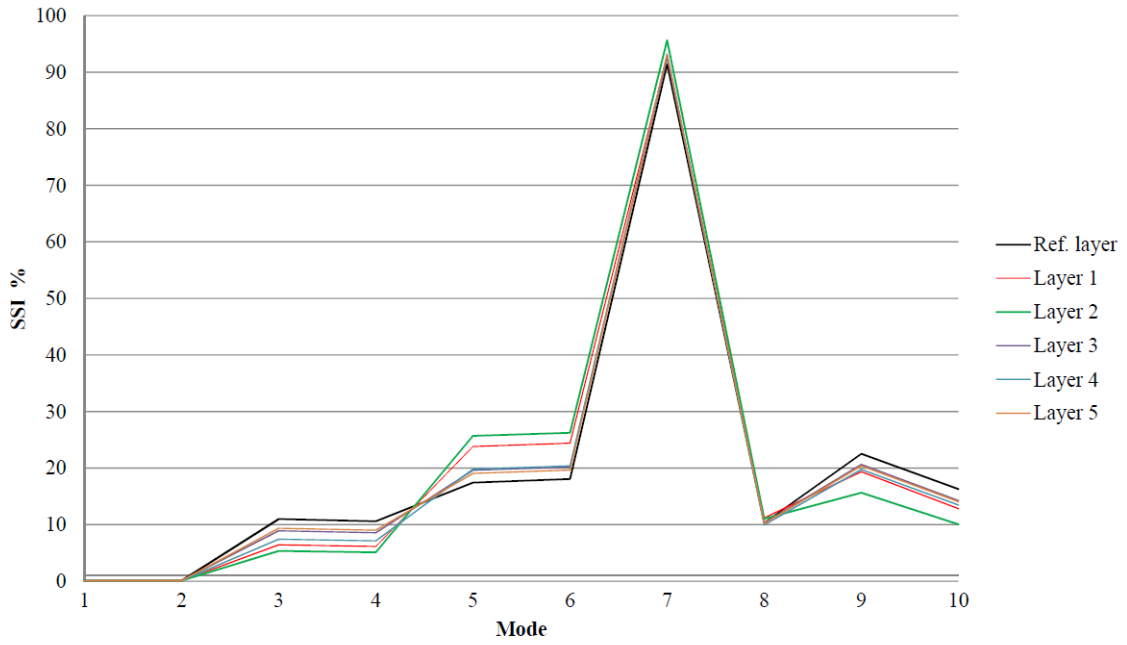


Figure 4.39: SSI-30%

The figure 4.40 shows that exists linear relation between the variations of Young's Modulus of each layers.

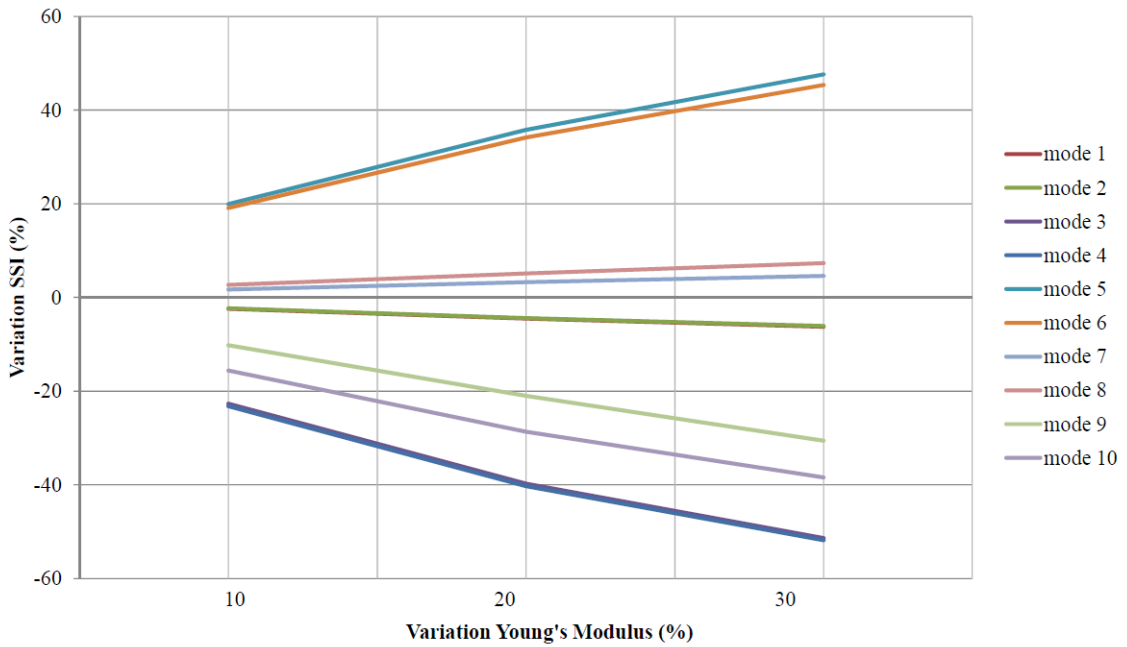


Figure 4.40: Comparison between variations of Young's modulus

CHAPTER 5

Conclusions and future works

5.1 Concluding remarks

In this study, the focus of this work is to evaluate the influence of the multi-layered strata on the magnitude of the soil-structure interaction (SSI) of gravity-based foundations.

By increasing linearly the Young's modulus 10%, 20% and 30%, the damping ratio produced by SSI are 19.92%, 35.77% and 47.63%, respectively. Evidently, from the analysis of the results presented, there is no linear relation between dynamic stiffness and damping ratios of SSI effect. Also it's important to highlight that the layer two is found to play a significant role related to the dynamic stiffness. The magnitude of the stiffness functions tend to increase when the mean Young's modulus of the soil profile increases, with the exception of the vertical mode, for which normalized impedance functions are largely independent of the soil profile. The obtained results confirm the necessity of considering the SSI effects for an accurate estimation of both the fundamental frequency and equivalent damping of the soil-structure system.

In conclusion, the impedance functions have been shown to strongly depend on the soil profile, which highlights the importance of estimating the ground real profile and the need of using it to accurately analyse the dynamic response of the foundation. This can be done by techniques such as MSASW (Multichannel Spectral Analysis of Surface Waves). Typically, this is often ignored or not done well in trials, and usually take samples to analyse static parameters, not dynamic parameters.

In projects, which are strongly influenced by the dynamic aspects (such as the limit state of fatigue in offshore structures) should pay more attention to the coherence of the tests that is asked to characterize the soil by certifiers (DNV-GL, for example).

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