

Strength design optimization of structural steel members according to Eurocode3

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Abstract

In order to design a steel member subjected to a bending moment and an axial load, there are an infinite number of possible solutions I- or H- steel cross-sections, the doubly-symmetric solution being just one of them. This paper presents a procedure to obtain the optimal steel cross-section from the infinite number of possible solutions. The process is based on the Reinforcement Sizing Diagrams employed in reinforced concrete strength design. The procedure looks for any type of solution regarding compact or non-compact steel sections. All aspects related to local instabilities will be taken into account, as well as special considerations in order to address the global instabilities associated with the slenderness of the steel element.

Notation

A	Cross-section area employed to compute $N_{b,Rd}$
A_t	Cross-section area
A_{teff}	Effective cross-section area for cross-sections in Class 4
A_1	Top flange area
A_2	Bottom flange area
E	Steel elastic modulus
M_y	External in-plane bending moment
$M_{b,Rd}$	Design buckling resistance moment of a laterally unrestrained beam
$M_{y,Ed}$	External in-plane bending moment applied to the section
$M_{y,Rk}$	Critical cross-section characteristic moment resistance about y-y axis
N	External axial load
$N_{b,Rd}$	Design buckling resistance of a compression member
N_{Ed}	External axial load applied to the section

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N_{Rk}	Critical cross-section characteristic resistance to normal force
$W_{eff,y}$	Effective section modulus about y-y axis, for Class 4 sections
$W_{el,y}$	Elastic section modulus about y-y axis
$W_{pl,y}$	Plastic section modulus about y-y axis
W_y	Appropriate section modulus employed in the computation of $M_{b,Rd}$
b_{fcomp}	Compressed flange width
b_{fb}	Bottom flange width
b_{ft}	Top flange width
d_w	Web height
h	Centroid height
f_y	Specified steel yield strength
k	Factor employed in the computation of the criterion to prevent the compression flange buckling in the plane of the web
l_b	Unbraced length of the beam-column member
t_{fb}	Bottom flange thickness
t_{ft}	Top flange thickness
t_w	Web thickness
χ	Reduction factor for the relevant buckling mode in compression
χ_{LT}	Reduction factor for lateral-torsional buckling
γ_{M1}	Partial safety factor for the building ζ Interaction factor

1. Introduction

Typical sections for beam-column members in steel edifications are usually I- or H- rolled sections. However, in other fields of steel constructions such as civil bridges, the selected cross-sections may be welded, since the higher demands to be supported by the structure calls for larger dimensions not possible for tabulated rolled sections. Whether edification or civil construction, designers tend to proportion their structures using symmetric sections, these being just one of the multiple solutions. Nevertheless, the optimal solution may not coincide with the symmetric one and important savings in the amount of steel used could be achieved. In this respect, environmental concerns constitute an important role because savings in steel consumption may be translated into significant reductions in greenhouse gas emissions.

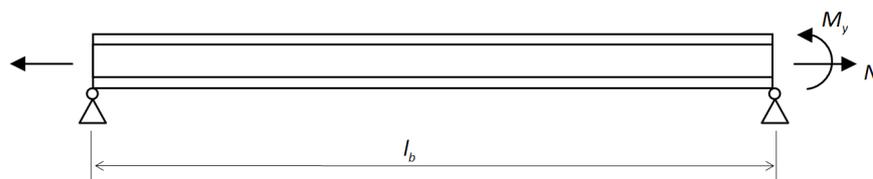


Figure 1. Conditions of the problem to be analyzed

The present work studies the optimal design of beam-column members subject to an external in-plane bending moment, M_y , and to an axial load, N , initially considered to be applied at the centroid of the web of the section (Figure 1). Figure 2 shows the employed nomenclature for the

cross-section of the element and the sign criteria for the applied external loads. Bending moment, M_y , acting on the strong axis of the cross-section will be considered positive when compressing the top flange of the section. The applied axial load, N , will be considered positive in tension. For the sake of simplicity, the fillets in rolled sections and throat thickness in welded sections have been ignored in the process. The different elements of the section are proportioned to provide sufficient strength and stiffness to resist the external actions and avoid premature buckling of the member. For non-compact sections, the plastic capacity will not be reached, so elastic capacity will be employed.

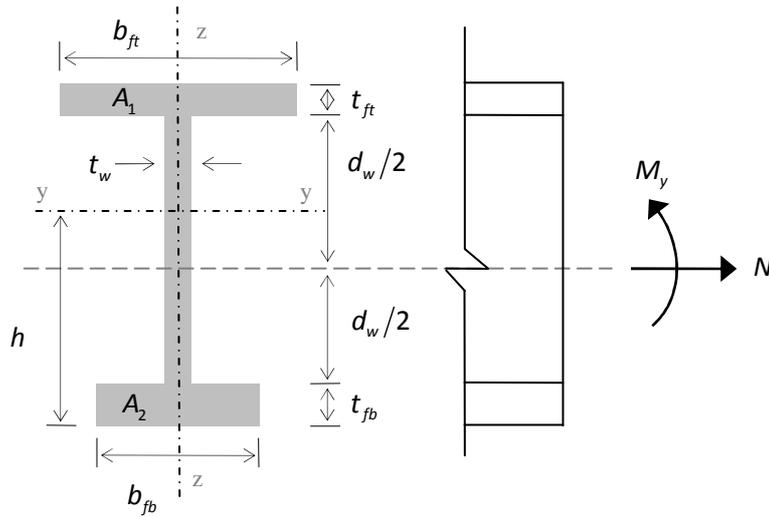


Figure 2. Nomenclature and sign criteria

The problem studied in this work has already been solved by Gil-Martín et al. [1] for Class 1 sections. Optimization was completed by using the RSD design approaches [2-3]. This methodology, originally conceived for reinforced concrete, represents the required reinforcement area for supporting a determined external loading as a function of depth of neutral axis in the concrete section (Figure 3). When applying RSD design approaches to optimization in steel sections, minor changes need to be made. Thereby, the graphics represent the cross-section area, A_t , as a function of the web height, d_w , and the optimal solution corresponds to the one with the lowest value for A_t (Figure 4).

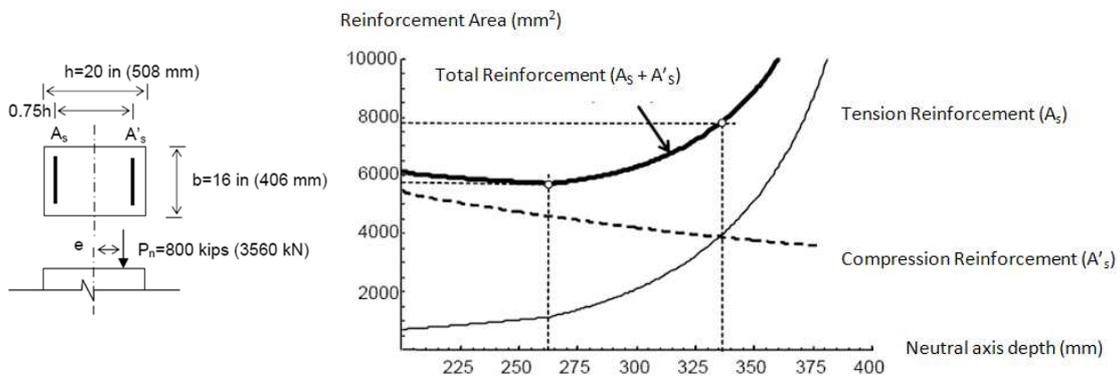


Figure 3. Example of RSD in a reinforced concrete section, from [4]

The present paper explains the well-developed process that was followed to obtain the optimal solution for any pair of (M_y, N) . The process makes it possible for the designer to choose the Class of the adopted cross-section; this is either compact or non-compact. Selecting the Class of the section is very important, for example, when designing a building for earthquake resistance according to Eurocode 8 (EC8) [5]. EC8 states that, for any given building subjected to an earthquake, the relation between its resistance and capacity for dissipating energy is related to the section classification (see Table 6.3 in EC8). Generally speaking, the more ductility needed the more compactness is required for the cross-section.

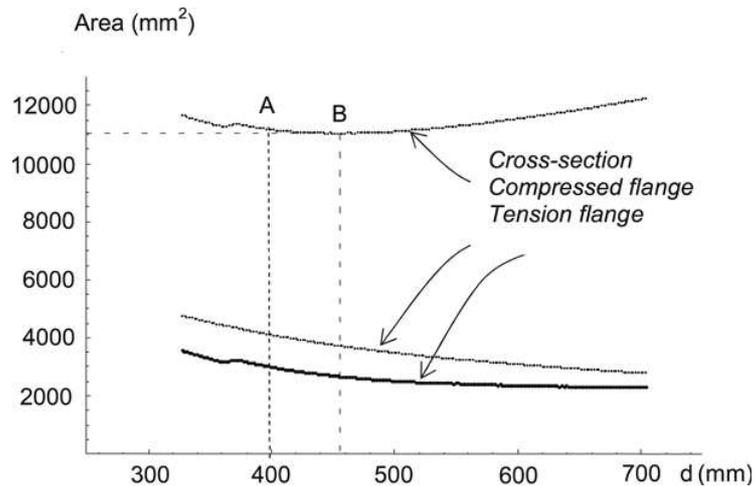


Figure 4. Example of RSD in a steel section: optimization of IPE500 under $M_{y,Ed} = 288$ kN m and $N_{Ed} = - 483$ kN with $t_f=16$ mm and $t_w=10,2$ mm. Point A represents the optimal solution and point B corresponds to IPE500. Taken from [1]

In contrast to the previous case is a composite roadway or highway bridge. These kinds of bridges, which also called “twin-girder bridges”, are composed of two longitudinal steel girders connected to the concrete slab of the deck by shear connectors. Twin-girder bridges are the most economical solution when covering span lengths in the range of 30 and 100 m [6], with special suitability between 60 and 80 m [7]. Considering these span lengths, self-weight becomes an important action to be withstood. Under this load, and beyond the complexity involving a composite section, cross-sections under positive moment at mid-span regions of composite bridges are usually in Class 1 or 2, since compression is carried mainly by the concrete deck. However, on internal supports, under negative moment, sections tend to be designed in Class 3 or 4 in order to avoid the excessive amount of steel that would be needed if those compressed sections were to be in Class 1 or 2 [8].

The typical section for these kinds of bridges is shown in Figure 5. The most usual range for H/L , being H the height of the I-section and L the covered span, is between 1/25 and 1/20 for highway or roadway bridges and 1/15 for railway bridges [6-7][9]. For a highway bridge with a span of 600 m, H would be between 2.5 and 3.0 m. This is due to the fact that the high dimensions of the sections do not allow the designer to choose them from the standard rolled sections and a welded design is needed. For these types of girders, the algorithm developed within this work lets the designer impose any constraint related to the dimensions of a particular element of the section, in this case, web height or even related to the Class of the cross-section.

The algorithm used to optimize the sections has been implemented in a computer program and some examples are presented here. The results obtained will be analyzed in order to test the validity of the process.

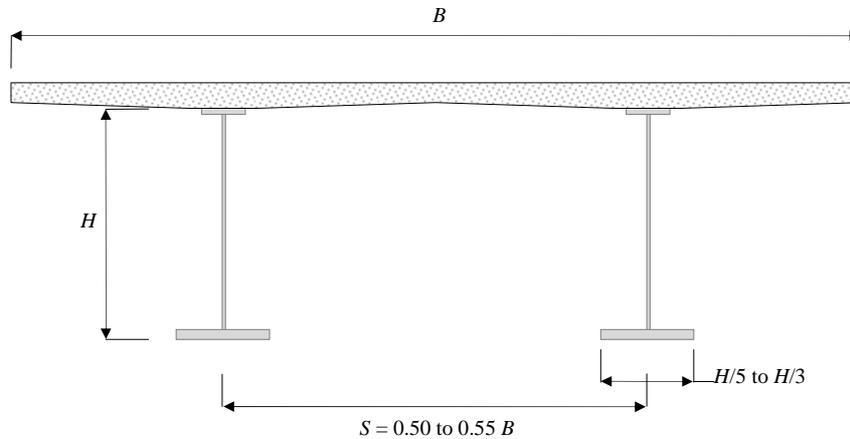


Figure 5. Typical section for a twin-girder composite bridge

2. The optimization procedure

As above explained, the optimization procedure to be presented in the current work is based on RSD methodology. This approach consists on the consideration of all the possible solutions for a design problem through a graphical representation that allows to choose the optimal one. In reinforced concrete members, usually the reinforcement area is represented in function of the neutral axis depth [2-3].

In steel construction, as was observed with reinforced concrete, an infinite number of solutions exist for the design of a steel cross-section subjected to combined loads N and M . These solutions can be presented using graphics similar to those used in the reinforced concrete RSD representation. In this case, the area of structural steel has been represented in function of the height of the web [1]. The main advantage of this procedure is that the engineering know all the possible cross-sections that resist a given combination of axial load and moment (N , M) making possible the choice, among all them, of the optimal one considering minimum weight, availability of steel shapes, simplicity on the job site, Class of the cross-section and so on.

The process followed during the optimization procedure is represented in the flow chart in Figure 6.

Section initial proportioning

The first step in the process is to select a fixed value for the web thickness, t_w , and a range of values for the height of the web, d_w . The range of d_w is obtained accounting both shear strength and shear buckling requirements. The flanges preliminary proportions are provided by equilibrium of forces acting on the cross-section, applying the axial load at the centroid of the web. The equilibrium is established by ignoring the web contribution and assuming that the forces carried by the top and bottom flanges act at the ends of the web and drive the flanges to the yield stress. Therefore, the sum of moments on either ends of the web results in Eq. 1:

$$A_1 \cdot f_y \cdot d_w + M_y - N \cdot \frac{d_w}{2} = 0$$

$$A_2 \cdot f_y \cdot d_w + M_y + N \cdot \frac{d_w}{2} = 0$$
(1)

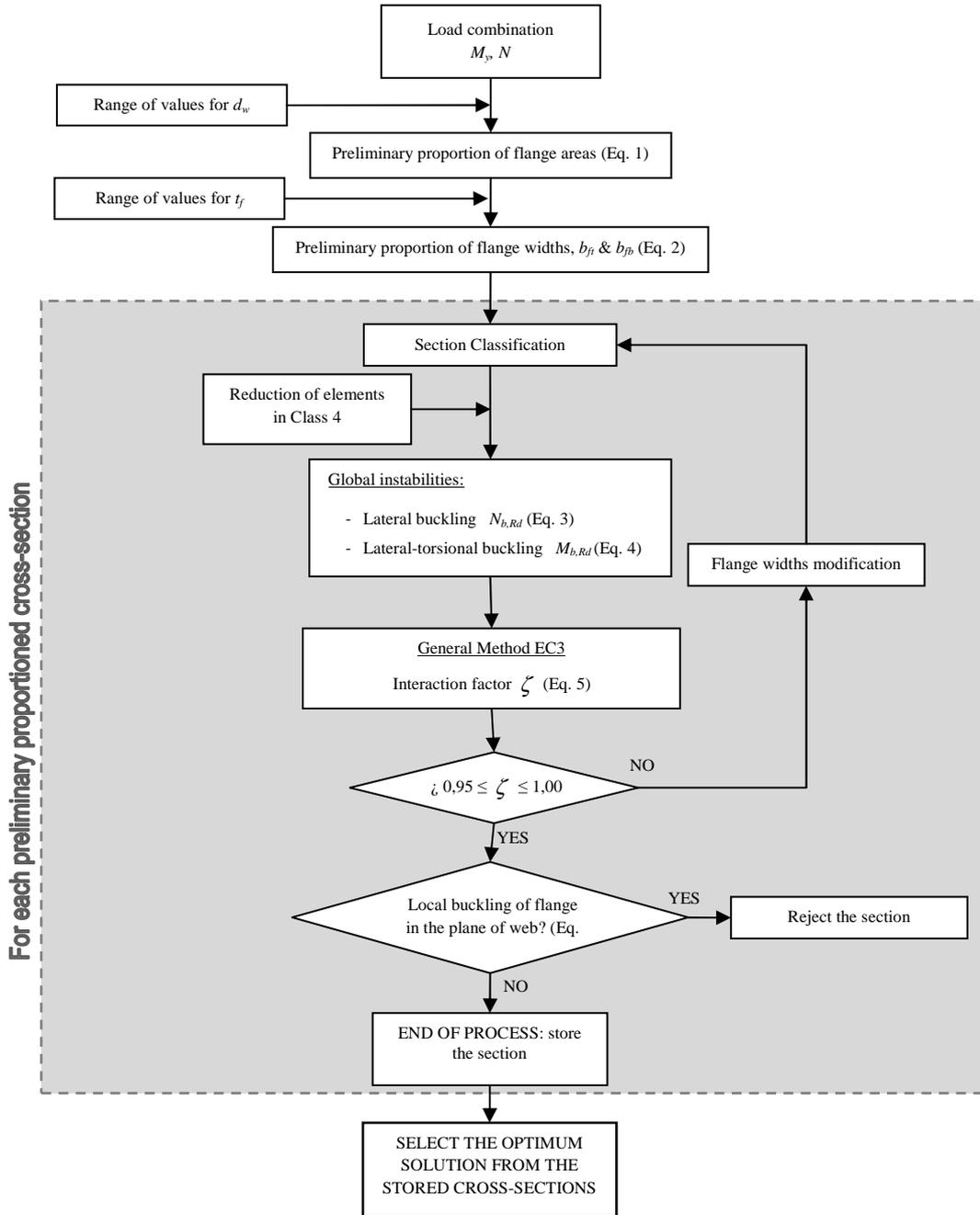


Figure 6. Flow chart explaining the entire process

Once A_1 and A_2 are known for each value of d_w , the next step is to choose another range of values for the flange thicknesses, t_{fi} and t_{fb} . Therefore, for each value of t_{fi} and t_{fb} the values of the flange widths can be obtained from Eq. 2:

$$b_{fi} = \frac{A_1}{t_{fi}} \text{ and } b_{fb} = \frac{A_2}{t_{fb}} \quad (2)$$

In the following, without loss of generality, the same thickness of both flanges has been considered, being, $t_{fi} = t_{fb} = t_f$.

Section classification

As described in Eurocode 3(EC3)[10], the role of cross-section classification is to identify the extent to which the resistance and rotation capacity of the cross-section is limited by its local buckling resistance. The classification of a determined cross-section will depend on the slenderness, i.e. the width to thickness ratio, of the parts subject to compression.

According to EC3, there are four classes for steel sections: Class 1, which can form a plastic hinge with the rotation capacity required from plastic analysis without reduction of the resistance; Class 2, similar to class 1 but with limited rotation capacity due to local buckling; Class 3, those sections in which local buckling appears before forming a plastic hinge and are assumed to work with an elastic distribution of stresses reaching the yield strength; and Class 4, in which local buckling is reached before elastic limit [11]. This classification may also be found in other codes as AISC Steel Construction Manual [12] with other terminology and slenderness limit values. Thereby, according to AISC, Class 1 and 2 sections are called compact sections; Class 3 sections are equivalent to non-compact sections; and Class 4 sections are similar to slender sections.

The limit values for the slenderness of each component of the section are given by Tables 5.2-1 and 5.2-2, presented in section 5 of Part 1-1 in EC3. According to these standard codes, the cross-section is classified according to the highest (least favorable) class of its compression parts.

Widths of the elements of the cross-section in Class 4 have to be reduced in order to their effective dimensions according to Part 1-5 of EC3.

Global instabilities at member level

Once the class of the cross-section is determined, it is necessary to calculate the resistance of the beam-column member to lateral buckling and lateral-torsional buckling due to axial load and bending moment, respectively. Following the formulas given in EC3 [9], the design buckling resistance of a compression member should be taken as:

$$N_{b,Rd} = \frac{\chi \cdot A \cdot f_y}{\gamma_{M1}} \quad (3)$$

where $A=A_t$ for cross-sections in Classes 1, 2, or 3, and $A=A_{teff}$ for cross-sections in Class 4 when subjected to uniform compression. The parameter χ is the reduction factor for the relevant buckling mode, computed as indicated in section 6.3.1. in Part 1-1 of EC3.

On the other hand, Section 6.3.2 of EC3 [9] provides the formula to calculate the parameter χ_{LT} , i.e. the reduction factor for lateral-torsional buckling. According to this, the design buckling resistance moment of a laterally unrestrained beam should be taken as:

$$M_{b,Rd} = \frac{\chi_{LT} \cdot W_y \cdot f_y}{\gamma_{M1}} \quad (4)$$

Here, W_y is the appropriate section modulus, taken as $W_{pl,y}$ for Class 1 or 2 cross-sections, $W_{el,y}$ for Class 3 cross-sections, and $W_{eff,y}$ for Class 4 cross-sections when only moment about the relevant axis is applied.

When the buckling resistances of the member are calculated, the General Method for lateral and lateral torsional buckling of structural components is applied. This method, explained in Section 6.3.4 of EC3 [9], allows the verification of the resistance to the former global instabilities of single members subject to compression and mono-axial bending in the plane. The member must fulfill Eq. 5 in order to achieve stability.

$$\frac{N_{Ed}}{\chi \cdot N_{Rk} / \gamma_{M1}} + \frac{M_{y,Ed}}{\chi_{LT} \cdot M_{y,Rk} / \gamma_{M1}} \leq 1 \quad (5)$$

where N_{Rk} and $M_{y,Rk}$ are the critical cross-section characteristic resistance to normal force and moment resistance about y-y axis. In this work, applied loads N_{Ed} y $M_{y,Ed}$ are:

$$M_{y,Ed} = M_y + (e_0 + e_{N_y}) N \quad (6)$$

$$N_{Ed} = N \quad (7)$$

Being e_{N_y} the shift of the relevant centroidal axis of the cross-section due to the widths reduction in class 4 when the member is subjected to uniform compression and e_0 the distance between the mid-height of the web –where the axial load is supposed initially applied at the gravity center of the gross-section (Figure 7), calculated as:

$$e_0 = h - (d_w / 2 + t_f) \quad (8)$$

In the above expression h is the height of the gravity centre of the cross-section.

In this work, the value for the sum presented in Eq. 5 has been called “interaction factor” and is represented by $\zeta = N_{Ed} / \chi \cdot N_{Rk} / \gamma_{M1} + M_{y,Ed} / \chi_{LT} \cdot M_{y,Rk} / \gamma_{M1}$.

Design adjustments

It is clear from the flow chart presented in Figure 6 that the proposed procedure is iterative. The dimensions of the cross-section are preliminary proportioned and classified. Afterwards, the General Method is applied to evaluate the stability of the member; because in most of the cases the preliminary cross-section will not be able to stand the applied loads without buckling, dimensions need to be modified. In this work, for each pair of values d_w - t_f , the width of the flanges, b_{f1} and b_{f2} , are adjusted until the member does not buckle, i.e. $\zeta \leq 1$. However, in order to gain optimal results, a lower limit has been imposed to ζ , so that the adjustments will be completed when $0.95 \leq \zeta \leq 1$. The adopted process for providing a cross-section of minimum

cross-sectional area, fulfilling all the stability considerations, is similar to the one followed by [1], and is explained below:

1. If $\zeta < 0,95$ the section provides excess capacity. To reduce the cross-sectional area, the widths of both flanges are reduced until:

$$0,95 \leq \zeta \leq 1 \quad (9)$$

2. If $\zeta > 1$ the section behavior is governed by instability. To provide sufficient strength, the flange areas must be increased. The approach to increase one flange or another depends on axial force and bending moment:

- a. If $M_y = 0$ or $N = 0$, the section is symmetric from the initial proportioning given by Eq. 1. The area of both flanges are increased the same amount until the condition given by Eq. 9 is fulfilled.

- b. If $M_y \neq 0$ and $N \neq 0$, the section from Eq. 1, the section will initially be asymmetric. In this case, one of the flange areas is increased in order to reduce the eccentricity given by Eq. 8 until the formula given by Eq. 9 is fulfilled:

- i. If M_y and N have an equal sign, the top flange width will increase.

- ii. If M_y and N have a different sign, the bottom flange width will increase.

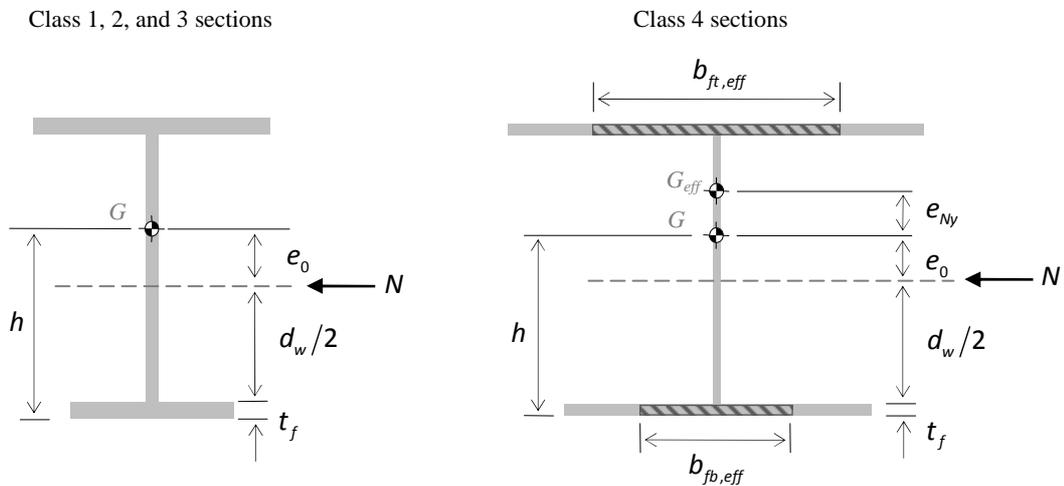


Figure 7. Values for the eccentricities e_0 and e_{Ny}

Once Eq. 9 is fulfilled for certain values of $d_w - t_{ft} - t_{fc}$ (in this example $t_f = t_{ft} = t_{fc}$), the cross-section will be stored if the dimensions of the flanges in compression are sufficient to prevent local buckling in the plane of the web. According to section 8 in Part 1-5 of EC3 [13], the following criterion should be met:

$$\frac{d}{t_w} \leq k \frac{E}{f_y} \sqrt{\frac{d_w \cdot t_w}{A_{fcomp}}} \Rightarrow b_{fcomp} \leq \frac{k^2 \cdot E^2 \cdot t_w^3}{f_y^2 \cdot t_f \cdot d_w} \quad (10)$$

The value of k should be taken as follows:

- Plastic rotation utilized $k = 0,3$
- Plastic moment resistance utilized $k = 0,4$
- Elastic moment resistance utilized $k = 0,55$

All the cross-sections with their corresponding pairs of d_w - t_f are stored. These solutions are sorted by cross-sectional area and the minimum is identified as the optimal solution. It is important to notice that the process may provide some solutions with the same optimal cross-sectional area. In this case, the final selected solution will be that with the minimum value of interaction factor ζ .

Furthermore, the procedure provides an infinite number of solutions (depending on the established constraints). The optimum (i.e. minimum cross-sectional area) or the symmetric solution is just one of the possible cross-sections that may be chosen [1-3].

3. Examples

The validity and effectiveness of the process have been tested and can be seen in the following three examples; in order to obtain minimum cross-sectional solutions for three combinations of M_y and N with the conditions represented in Figure 1: a simple supported beam with end-fork conditions (i.e. pin supported end and free warping). The applied load combinations correspond to three points in the interaction equation (Figure 8) corresponding to a specimen made of steel Grade 235 ($f_y = 235 \text{ N/mm}^2$) with a cross-section HEB600 ($d_w = 540 \text{ mm}$; $t_w = 15,50 \text{ mm}$, $t_f = 30 \text{ mm}$; $b_{ft} = b_{fb} = 300 \text{ mm}$; $A_t = 27000 \text{ mm}^2$) and an unbraced length, l_b , equals to 6,00 m. The load combinations are presented in Figure 8.

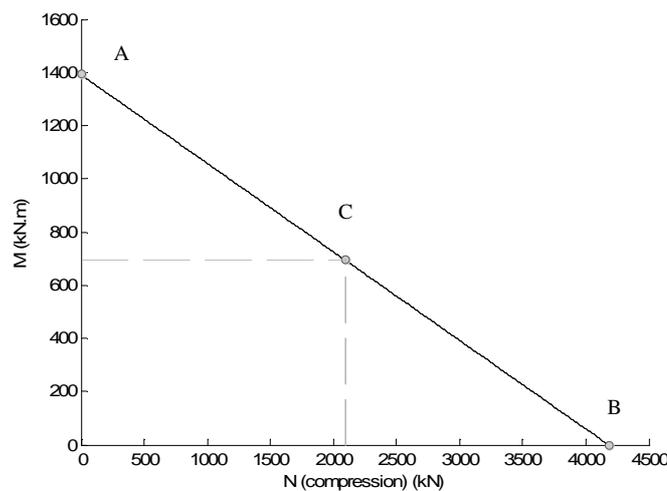


Figure 8. Interaction equation corresponding to HEB600, for $f_y = 235 \text{ N/mm}^2$, $l_b = 6 \text{ m}$ and $\psi = 0$

3.1. Combination A: $M_y=1391.60 \text{ kN}\cdot\text{m}$ -bending moment applied on the right support of the beam-

The first combination of loads corresponds to point A in Figure 8, simple strong axis bending with a value of $M_y=1391,60 \text{ kN}\cdot\text{m}$. Figure 9 shows the obtained design solutions for different web depths, d_w , with a range from 50 mm to 2000 mm with a step of 5 mm. The adopted range of values for flange thicknesses, t_f , varies from 4 mm to 40 mm, with a step of 2 mm. The HEB 600 web thickness ($t_w = 15,50 \text{ mm}$) is adopted for every solution. According to Eq. 1, if $t_f = t_{ft} = t_{fb}$ all the obtained solutions are doubly-symmetric (i.e. $b_{ft} = b_{fb}$). The results from Eq. 1 are presented as a continuous line. Dots in Figure 9 correspond to the solutions obtained after the adjustment process for the four different Classes of the cross-section. To distinguish between each class- different- have been used, respectively. In Figure 9 the solution corresponding to the HEB section and the optimal ones obtained for each class using the optimization procedure have been identified. As may be observed from Figure 9, the initially proportioned dimensions for the elements of the cross-section given by Eq. 1 are subsequently modified by the adjustment process. In some cases, those dimensions have been overestimated since the contribution of the web was ignored in Eq. 1. However, many solutions have cross-sectional areas greater than initially estimated due to the fact that members turned out unstable and buckled and therefore dimensions need to be modified in order to get sufficient strength to withstand the applied loads.

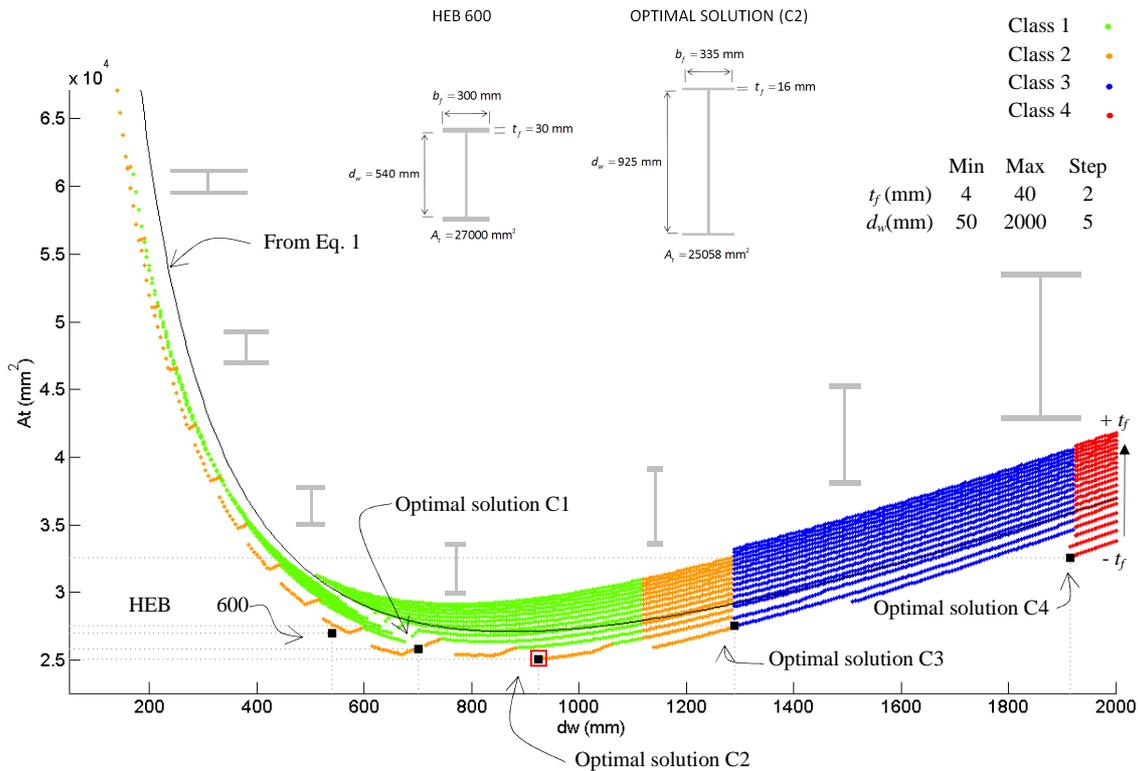


Figure 9. Cross-sectional area A_t of the solutions in terms of web depth d_w for strong axis bending moment

The solution with the lowest cross-sectional area corresponds to:

$$d_w = 925 \text{ mm}; t_w = 15,50 \text{ mm}; t_f = 16 \text{ mm}; b_{ft} = b_{fb} = 335 \text{ mm}; A_t = 25058 \text{ mm}^2$$

The web and top flange Classes are 1 and 2 respectively, leading to cross-section Class 2. The interaction factor is $\zeta = 0,9989$.

Figure 10 shows the optimal solution for each Class according to EC3 and compares their cross-sectional area with the one of HEB 600. The table in Figure 10 provides the dimensions for these optimal solutions. Class 1, 2, and 3 sections reduce the flange width, b_f , when increasing web depth, d_w , while in Class 4 b_f increases since web is reduced for local buckling. In this case, only compact solutions (Classes 1 and 2) provide less cross-sectional area than the standard HEB600. Figure 9 shows that a saving of 7,2 % with respect to the area of HEB600 can be obtained.

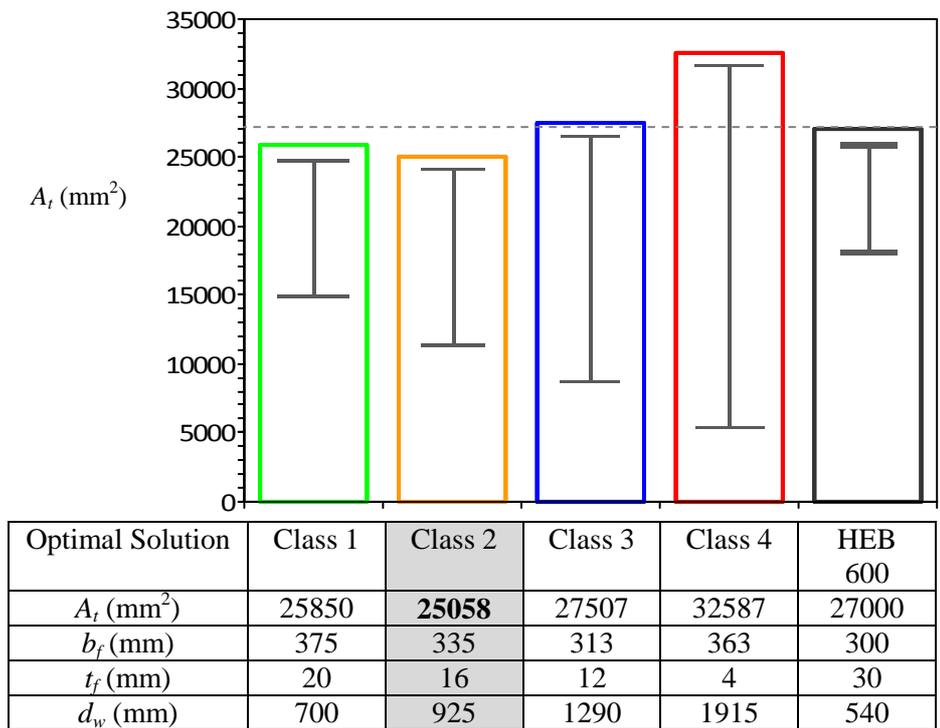


Figure 10. Comparison between the dimensions of different optimal solutions for each Class and HEB 600, for strong axis bending moment. Scale of dimensions sketches: 1/400

In Figure 11 the obtained results from the optimization process imposing $t_f = 30$ mm (flange thickness of HEB600) have been represented for both welded and rolled sections. This figure shows that if welded sections are considered instead of rolled sections, areas slightly larger are obtained. These differences are due to the different values of the imperfection factors corresponding to the buckling curves that are different for both welded and rolled sections. For this example no welded solution exists with a cross-sectional area under 27000 mm² - HEB600 cross-section area- while if a rolled section is employed an area $A_t = 26098$ mm² is obtained (for $d_w = 805$ mm and $b_f = 227$ mm).

Figure 11 shows that the curve corresponding to rolled sections almost matches the solution corresponding to the HEB 600. These small differences are due to the fact that, as was explained earlier, in this work the fillets in rolled sections are not taken into account.

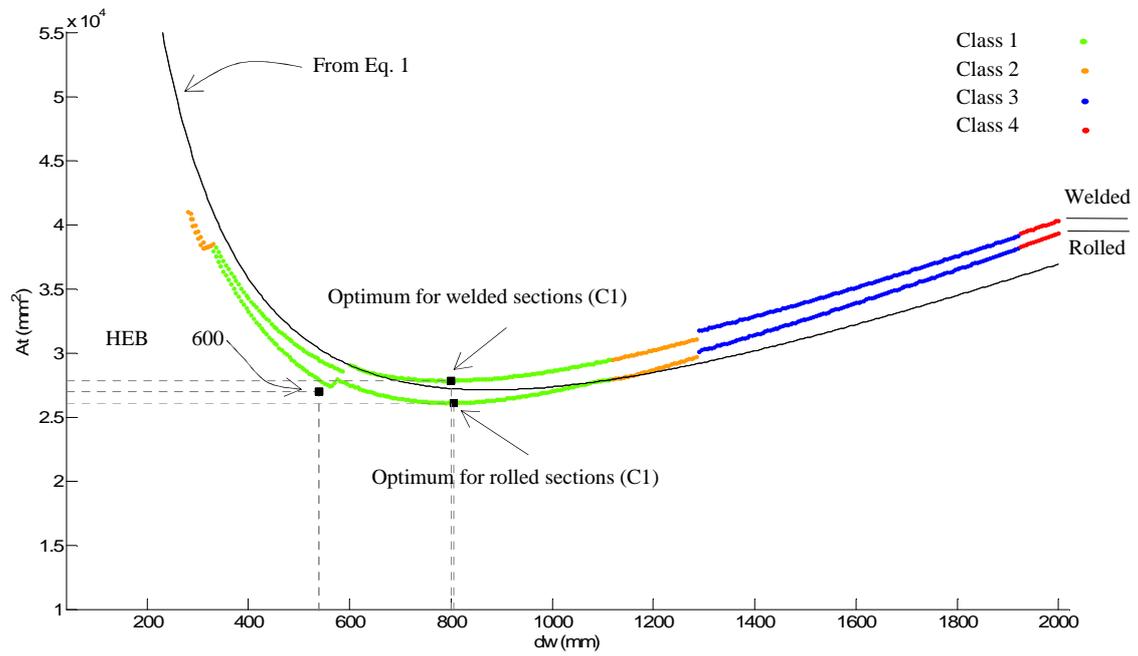


Figure 11. Cross-sectional area A_t of the solutions with $t_f = 30$ mm in terms of web depth d_w for strong axis bending moment employing welded and rolled sections imperfection factors

3.2. Combination B: $N = -4180.80$ kN (compression)

In this case, the steel section member is subject to a pure compression with a value of $N = -4180,80$ kN . This load combination corresponds to point B in Figure 8, i.e. the buckling capacity of the considered HEB 600 member. The results for the different values of d_w , with a range from 50 mm to 800 mm with a step of 5 mm, are presented in Figure 12. Again, the HEB 600 web thickness ($t_w = 15,50$ mm) is adopted for every solution. The adopted range of values for flange thicknesses, t_f , starts at 4 mm and finishes at 40 mm, with a step of 2 mm. The obtained optimal solution corresponds to $d_w = 215$ mm; $t_w = 15,50$ mm $t_f = 18$ mm; $b_{ft} = b_{fb} = 492$ mm; $A_t = 21045$ mm². This solution saves a 22,05 % of steel with respect to the HEB600. The cross-section Class is 3 due to the slenderness ratio for the flanges in compression: $10\varepsilon < \frac{c}{t} = 13.23 < 14\varepsilon$. The interaction factor for this solution is $\zeta = 0,9992$.

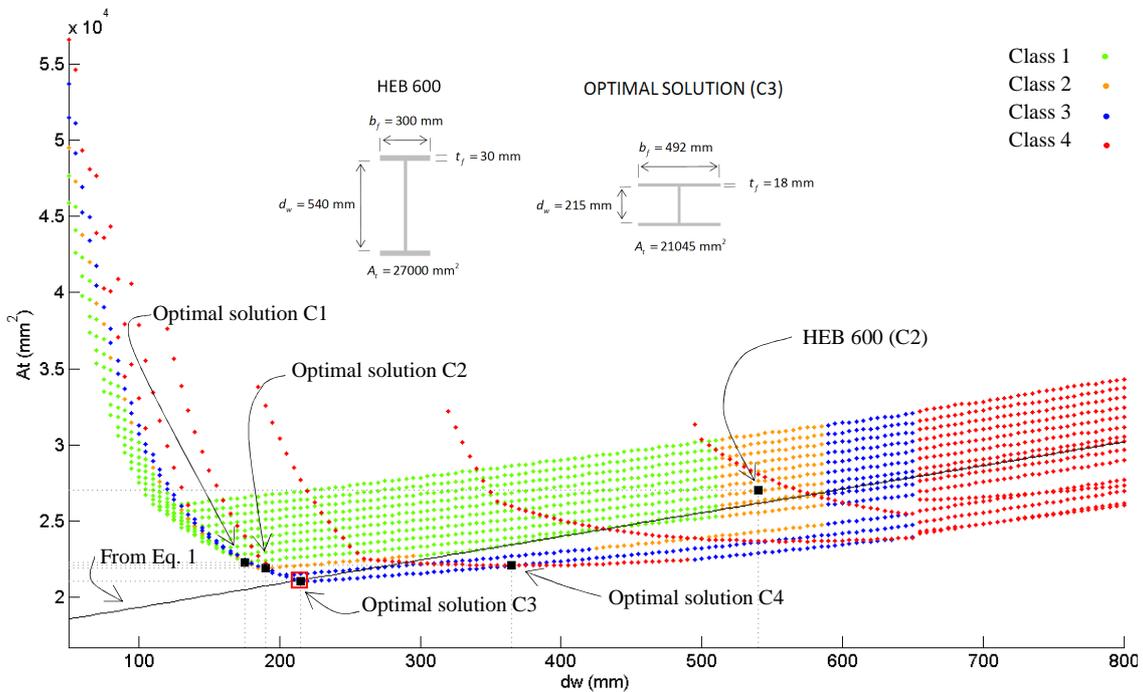


Figure 12. Cross-sectional area A_t of the solutions in terms of web depth d_w for pure compression

As in the former example, Figure 13 shows the optimal solution for each Class. In this particular case, all the optimal solutions have cross-sectional areas smaller that the one corresponding to the standard HEB600. As in the previous example, Eq. 1 provides symmetric solutions since, the only applied load there is now is the compressive axial load. Because the areas of the flanges are not affected by web depth, d_w , the flange widths, b_f , will be the same for every fixed value of the flange thickness, t_f . Figure 14 shows the evolution of the flange width, b_f , as function of the depth of the web, d_w , for a fixed value of the flange thickness, $t_f = 30$ mm . The obtained optimal solution corresponds to a web depth $d_w = 145$ mm and a flange width $b_{ft} = b_{fb} = 357$ mm . The corresponding cross-sectional area is $A_t = 23668$ mm².

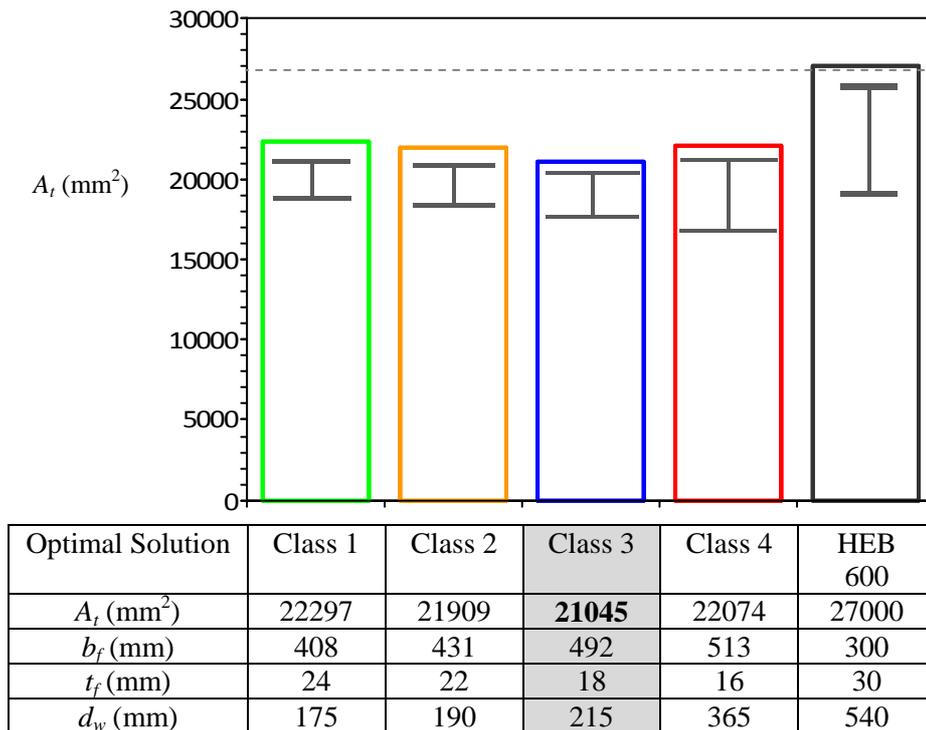


Figure 13. Comparison between dimensions of different optimal solutions for each Class and HEB 600, for pure compression.

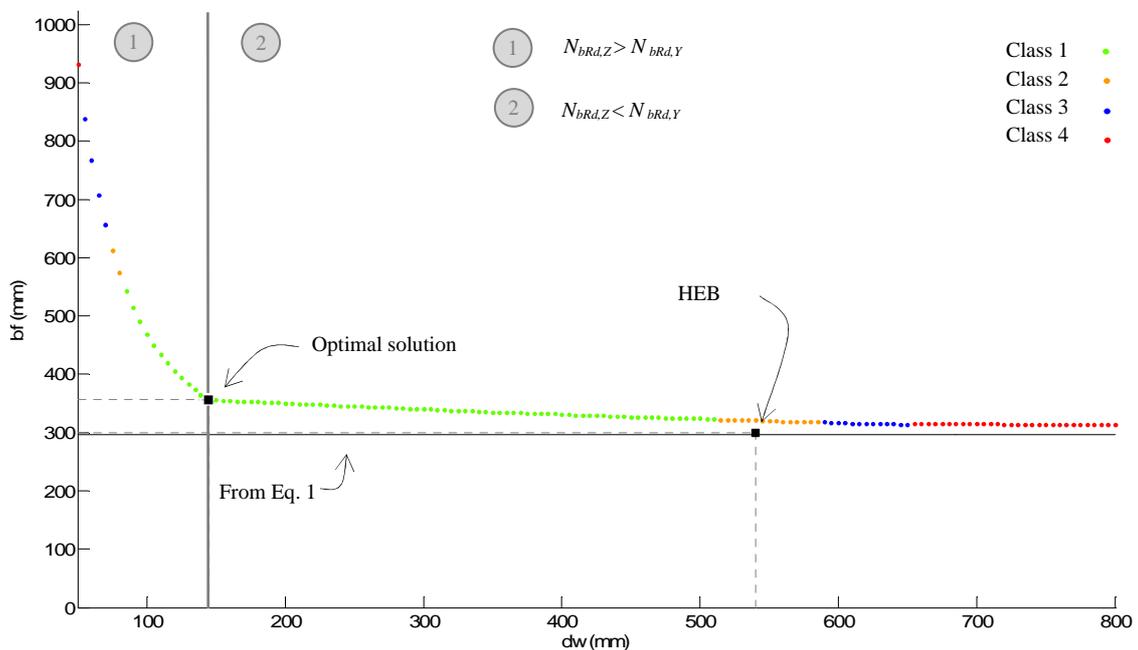


Figure 14. Flange width, b_f , for the solutions of flange thickness $t_f = 30$ mm in terms of web depth d_w for pure compression

In Figure 14 two regions appear. Region 1 corresponds to solutions where the relevant mode for lateral buckling under compression is flexural buckling (solutions are symmetric) about y-y axis. In this Region, solutions need to increase their preliminary proportioned flange width by an important amount before reaching stability, because the relevant mode is governed by the

moment of inertia about y-y, which is proportional to b_f : $I_y \propto b_f$ (\propto meaning being proportional). However, $I_y \propto d_w^3$, resulting in much less wider solutions as d_w becomes deeper. On the other hand, Region 2 corresponds to flexural buckling under z-z axis and solutions get quick stability since $I_z \propto b_f^3$, and solutions need to increase lightly their preliminary proportioned flanges. In this Region, the slope of the curve becomes much flatter as d_w increases since now $I_z \propto d_w$.

3.3. Combination C: $M_y= 695.82 \text{ kN.m}$ & $N= -2090.41 \text{ kN}$ (compression)

This case corresponds to a combination of simultaneous compression and bending moment about the strong axis. Point C in Figure 8 coincides with half compression and bending moment capacity of the standard HEB 600 adopted as a benchmark problem. Solutions have been obtained again for the same range of values for web depth, d_w , and flange thickness, t_f , as in the previous example. The value of the web thickness, t_f , is 15,5 mm. Figure 15 shows the results obtained and the optimal section, for which the dimensions are: $d_w = 585 \text{ mm}$; $t_w = 15,50 \text{ mm}$ $t_f = 22 \text{ mm}$; $b_{ft} = 433 \text{ mm}$; $b_{fb} = 334 \text{ mm}$; $A_t = 25942 \text{ mm}^2$. For this section, both top flange and web are Class 2, and the entire cross-section results in that Class. The solution saves a 4 % of steel with regards to the standard HEB 600.

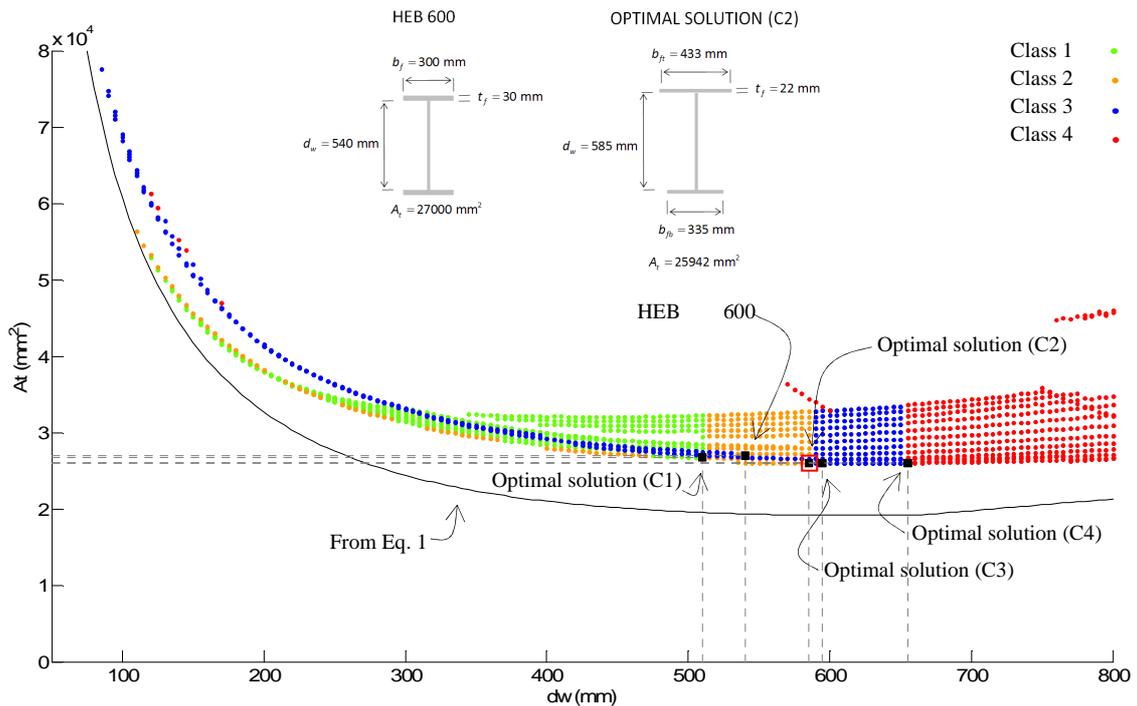


Figure 15. Cross-sectional area A_t of the solutions in terms of web depth d_w for simultaneous compression and bending moment about strong y-y

Figure 16 shows the obtained optimal results for each Class of sections. In this case, as in the former example, once again, all of them have a less cross-sectional area than the standard HEB600. There are two of them, solutions for Classes 2 and 3, which are almost the same area (slight differences in dimensions of flanges and web result in just 1 mm² less in cross-sectional area for solution in Class 2).

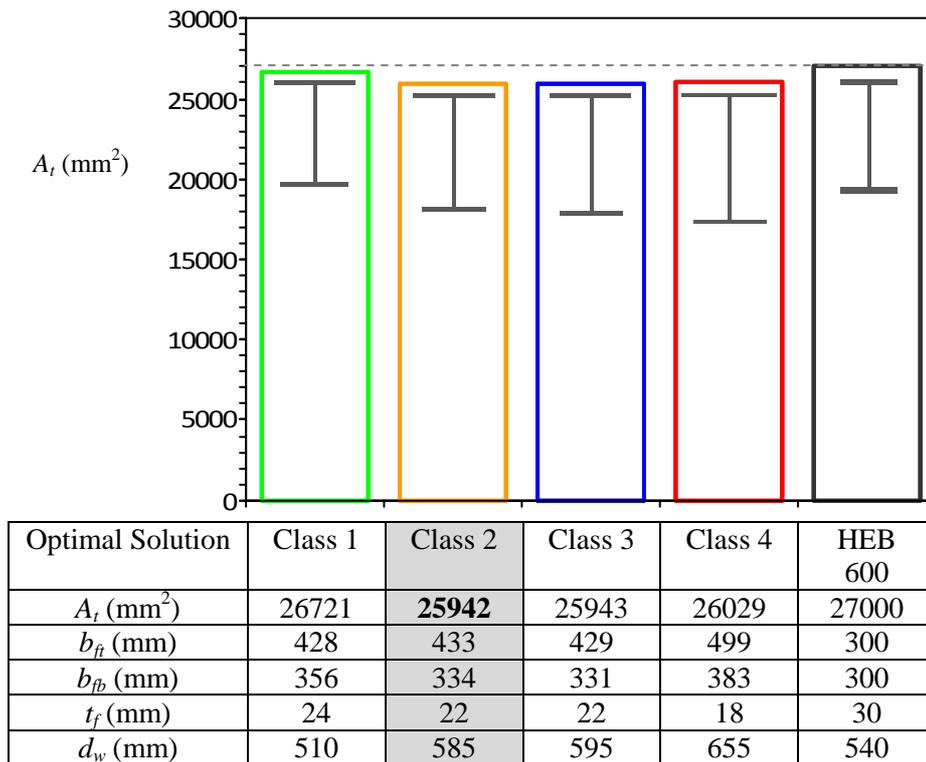


Figure 16. Comparison between the dimensions of different optimal solutions for each Class and HEB 600, for simultaneous compression and bending moment about strong y-y.

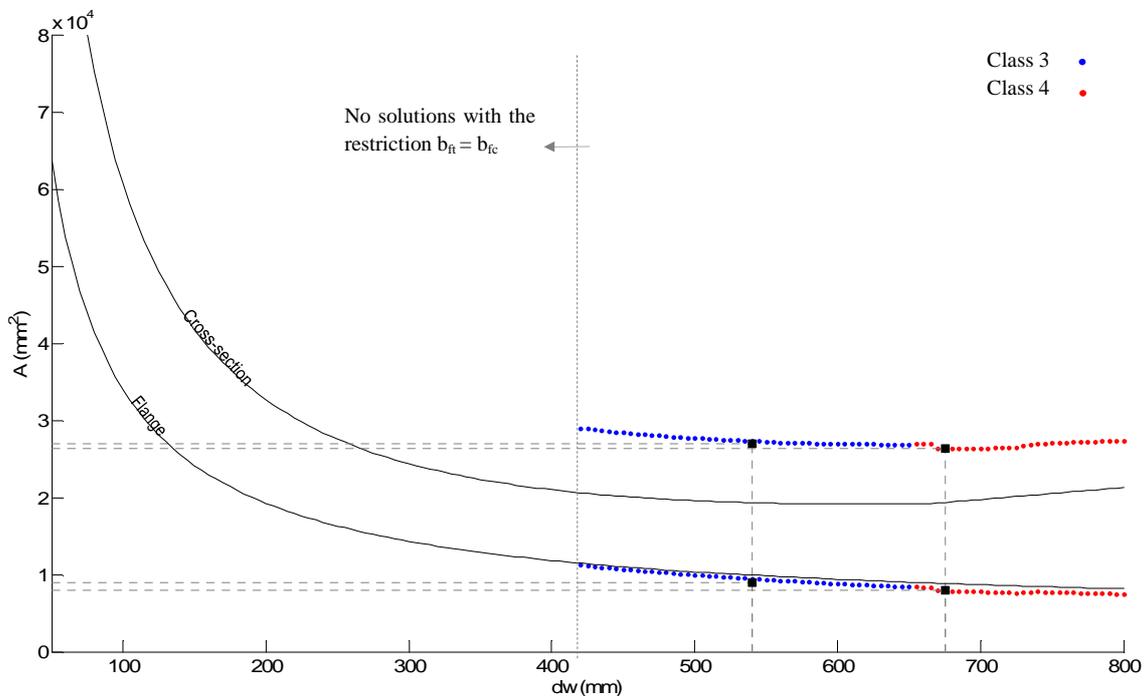


Figure 17. Cross-sectional and flange area in terms of d_w , for solutions of $t_f = 20$ mm and forcing both flanges to be equal (i.e. doubly-symmetrical cross-section) for simultaneous compression and bending moment about strong y-y.

As the procedure is completely general, the doubly-symmetrical cross-section may be extrapolated without loss of generality. If the width of both flanges are forced to be equal, the optimal solution corresponds to a flange thickness of $t_f = 20$ mm and $d_w = 625$ mm; $t_w = 15,50$ mm $b_{ft} = 396$ mm; $b_{fb} = 396$ mm; $A_t = 26303$ mm². Figure 17 represents both the cross-sectional and flange areas for doubly-symmetrical cross-section with $t_f = 20$ mm in function of the height of the web. For this figure it is evident that solutions only exist for values of d_w from 420 mm, being the sections in Class 3 or 4. The standard HEB600 is included in the list of possible solutions in Class 2.

3.4. Global optimization

In order to extend the former optimization procedure to other values of web's thickness, t_w , the above process has been applied to several values of t_w between 6 mm and 19 mm for the axial compression and bending moment about the strong axis denoted as combination C (see Figure 8). The optimal cross-section (i.e., with minimum area) obtained for each class of cross-section [9] for each thickness of the web can be identify in Figure 18. This figure shows that the smallest area that fulfil all the EC3 [9] requirements corresponds to cross-section in class 4 with $t_w = 8$ mm. This optimal section needs to be stiffened because the slenderness of the web is too high. The optimum cross-section in class 3 and in Class 1 and 2 appears for $t_w = 13,5$ mm and $t_w = 14,5$ mm, respectively. In such cases the slenderness of the web is low enough that transverse stiffeners are not needed. In Figure 18, the optimal solutions obtained for the value of the thickness of the web adopted in the former sections (t_w of the standard HEB 600) have also been indicated.

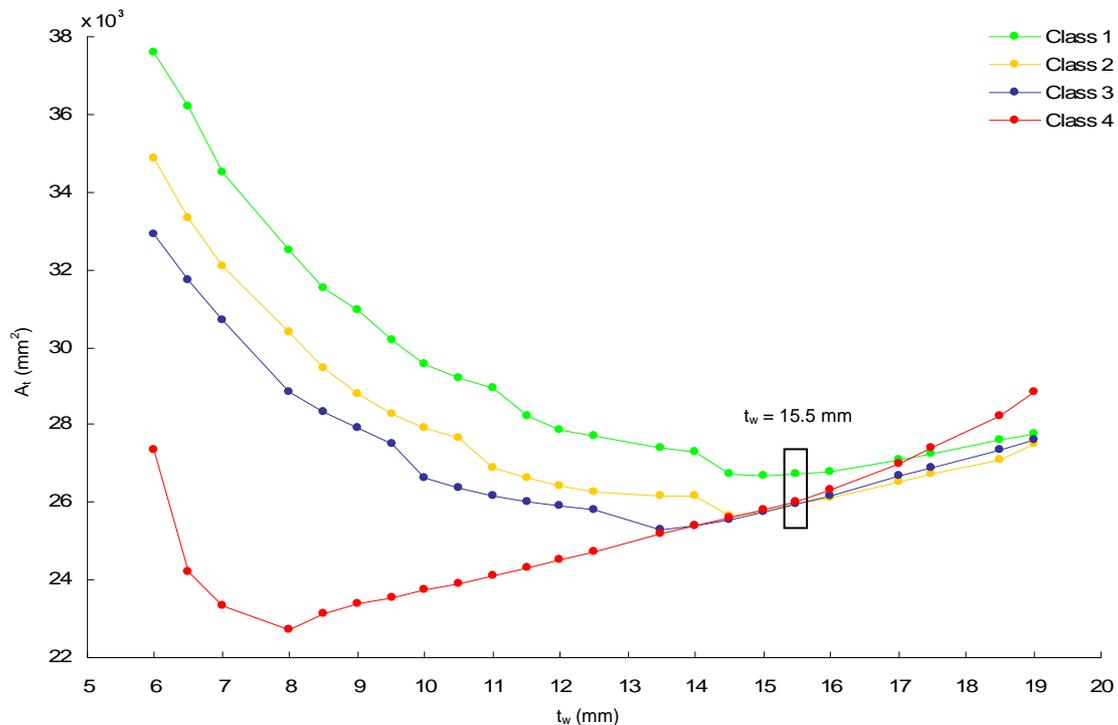


Figure 18. Optimal (i.e. minimum) cross-sectional area in terms of t_w obtained for each class of cross-section and for simultaneous compression and bending moment about strong y-y.

4. Conclusions

As has been explained and demonstrated in this work, employed symmetrical cross-sections are usually not, in most of the cases, the optimal solutions. This work presents an iterative procedure in order to get the optimal solution for the I-shaped cross-section of a steel beam-column member subject to an external axial load and bending about strong axis. The process is based on RSD diagrams for optimizing the longitudinal reinforcing steel in reinforced concrete sections and completes the procedure proposed by Gil-Martín et al. [1] for obtaining these optimal solutions with steel sections in Class 1 according to Eurocode 3. This method allows engineers to choose among all the possible solutions: compact, non-compact and slender sections, obtaining important savings in steel and hence leading to reductions in greenhouse gas emissions.

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