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2	assessment of running stride kinematics at different velocities
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validity of the Stryd[™] system for measuring spatio-temporal variables during running at 21 22 different velocities (8-20 km.h⁻¹) by comparing data with another widely-used device (the OptoGait[™] system). Eighteen trained male endurance runners performed an incremental 23 running test (8-20 km. h⁻¹ with 3 min stages) on a treadmill. Spatio-temporal parameters 24 25 (contact time [CT], flight time [FT], step length [SL], and step frequency [SF]) were measured using two different devices (Stryd[™] and OptoGait[™] systems). The Stryd[™] 26 system showed a CV <3%, except for FT (3.7-11.6%). The OptoGait[™] achieved CV <4%, 27 except for FT (6.0-30.6%). Pearson correlation analysis showed large correlations for CT 28 29 and FT, and almost perfect for SL and SF over the entire protocol. The intra class 30 correlation coefficients partially support those results. Paired t-tests showed that CT was underestimated (p<0.05, ES>0.7; ~4-8%), FT overestimated (p<0.05, ES>0.7; ~7-65%), 31 while SL and SF were very similar between systems (ES<0.1, with differences <1%). The 32 Stryd[™] is a practical portable device that is reliable for measuring CT, FT, SL, and SF 33 during running. It provides accurate SL and SF measures but underestimates CT (0.5-8%) 34 and overestimates FT (3-67%) compared to a photocell-based system. 35

36

Key words: biomechanics; reliability; running; technology; validity

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Word count: 2,829 38

39 Introduction

Interest in running gait analysis is appropriate in both an injury prevention (11,17) and an athletic performance context (1,3,13,18). While previous methods of analysis have generally required well-equipped research laboratories, recently, there has been a move to produce low-cost, portable gait analysis equipment. This has allowed researchers to remove participants from an artificial laboratory environment and measure participants in a more natural environment (14).

46

In the current study the authors compared StrydTM data with a widely-used device for 47 assessing spatio-temporal variables during locomotion. The OptoGait[™] system is 48 composed of photoelectric cells positioned along transmitting receiving bars of 1 m in 49 50 length with a maximum distance of 6 m between bars. The transmitting-receiving bars 51 contain infrared LED diodes, enabling communication between the two bars. When a 52 subject passes between the transmitting bar and the receiving bar, the system 53 automatically calculates spatio-temporal parameters by sensing interruptions in 54 communication. The assessment results of this gait analysis system have been previously 55 validated in healthy adults walking at a comfortable speed (9) and the system has been 56 used to examine spatio-temporal parameters of athletes when running at different 57 velocities and under different conditions (12,16).

58

59 Stryd system[™] (www.stryd.com) is a pioneer in manufacturing wearable power meters 60 for running. Power meters have helped performance-focused cyclists revolutionize their 61 training and racing (15), and the same may soon be accomplished for runners. This power 62 meter for runners is a foot pod that attaches to a running shoe to measure twelve metrics 63 to quantify performance: pace, distance, elevation, running power, form power, cadence, ground contact time, vertical oscillation, leg stiffness. This is a relatively new tool, and
there is not yet data to demonstrate validity and reliability of this device, making this type
of study beneficial.

67

The variety of available technologies for gait analysis (e.g., accelerometers, gyroscopes, 68 force plates, pressure plates, and photoelectric cells) implies a variety of devices should 69 70 exist for analyzing stride characteristics. However, some of these devices have not yet 71 been validated. The validity and reliability of a gait analysis system are essential to 72 determine whether results are due to changes in gait pattern or are simply systematic 73 measurement errors. Therefore, the aim of the current study is to determine the absolute 74 reliability (within-subject variation) and to evaluate the concurrent validity of the Stryd[™] 75 system for measuring spatio-temporal variables during running at different velocities 76 (usual for endurance runners at training and competing, 8-20 km.h⁻¹) by comparing data with a widely-used device for this purpose (i.e., the OptoGait[™] system). 77

78

79

80 Methods

81

82 Experimental approach to the problem

With the introduction of new wireless devices, establishment of their reliability and
validity are essential before practical use. In this study, the StrydTM system was compared
to the OptoGaitTM system for measuring spatio-temporal variables during running at
different velocities (8-20 km.h⁻¹).

87

88 Participants

89 A group of eighteen recreationally trained male endurance runners (age range: 19-46 90 years; age: 34 ± 7 years; height: 1.76 ± 0.05 m; body mass: 70.5 ± 6.2 kg) voluntarily 91 participated in this study. All participants met the inclusion criteria: (1) older than 18 92 years old, (2) able to run 10 km in less than 40 minutes, (3) training on a treadmill at least once per week, (4) not suffering from any injury (points 3 and 4 related to the last 6 93 94 months before the data collection). After receiving detailed information on the objectives 95 and procedures of the study, each subject signed an informed consent form in order to participate, which complied with the ethical standards of the World Medical 96 97 Association's Declaration of Helsinki (2013). It was made clear that the participants were 98 free to leave the study if they saw fit. The study was approved by the Ethics Committee 99 of the San Jorge University (Zaragoza, Spain).

100

101 **Procedures**

The study was conducted in June 2017. At the time of these observations, the subjects had completed between 6-7 months of training. Subjects were individually tested on one day (between 16:00 and 21:00 h). Prior to all testing, subjects refrained from severe physical activity for at least 48 h and all testing was at least 3 h after eating. Tests were performed with the subjects' usual training shoes to measure their typical performance.

107

Subjects performed an incremental running test on a motorized treadmill (HP cosmos Pulsar 4P, HP cosmos Sports & Medical, Gmbh, Germany). The initial speed was set at 8km.h⁻¹, and speed increased by 1 km.h⁻¹ every 3 min until running speed reached 20 km.h⁻¹. The slope was maintained at 1% (0.9°). The treadmill protocol was preceded by a standardized 10-min accommodation programme (5 min walking at 5 km.h⁻¹, and 5 min running at 10 km.h⁻¹). Athletes were experienced in running on a treadmill.

115 Materials and testing

i) Anthropometry. For descriptive purposes, height (cm) and body mass (kg) weremeasured.

118

ii) Biomechanics. Spatio-temporal parameters were measured using two differentdevices:

121 _ The OptoGait[™] system (Optogait; Microgate, Bolzano, Italy) was previously validated for the assessment of spatio-temporal parameters of the gait of young 122 adults (9). As indicated by Lee et al. (9), the OptoGait[™] achieved a high level of 123 correlation with all spatio-temporal parameters by intra-class correlation 124 125 coefficients (0.785–0.952), coefficients of variation (1.66–4.06%), standard error 126 of measurement (2.17–5.96%), and minimum detectable change (6.01–16.52%). 127 The system detects any interruptions and therefore measures both CT and FT with 128 a precision of 1/1000 s. The two parallel bars of the device system were placed on 129 the side edges of the treadmill at the same level as the contact surface. Contact time (CT), flight time (FT), step length (SL), and step frequency (SF or cadence) 130 131 were measured for every step during the treadmill test, and were defined as 132 follows:

133

134

• CT (s): time from when the foot contacts the ground to when the toes lift off the ground.

- 135 o FT (s): time from toe-off to initial ground contact of consecutive footfalls
 136 (e.g., right-left).
- 137 o SL (m): length the treadmill belt moves from toe-off to initial ground
 138 contact in successive steps.

139		• SF or cadence (steps/min): number of ground contact events per minute.
140	-	Stryd [™] (Stryd Powermeter, Stryd Inc. Boulder CO, USA): a relatively new device
141		which estimates power in watts. Stryd ^{TM} is carbon fibre-reinforced foot pod
142		(attached to your shoe) that weights 9.1 grams. Based on a 6-axis inertial motion
143		sensor (3-axis gyroscope, 3-axis accelerometer), this device provides spatio-
144		temporal data including CT and SF. From CT and SF, in addition to running
145		velocity, the authors calculated FT and SL as follows:

146 (1) FT(s) = step time(s) - CT(s),

where step time is the time from the beginning of the step cycle (take-off) to theend (previous frame to take-off),

151

152 Statistical analysis

Descriptive statistics are represented as mean (SD). Tests of normal distribution and 153 154 homogeneity (Shapiro-Wilk and Levene's test, respectively) were conducted on all data 155 before analysis. Coefficient of variation (CV, %) and standard error of the mean (SEM) were calculated as a measure of absolute reliability (within-subject variation and standard 156 deviation of a sampling distribution, respectively) (2,6). Intra class correlation 157 coefficients were calculated between OptoGait[™] and Stryd[™] data for each spatio-158 159 temporal variable analysed (CT, FT, SL, and SF). Values less than 0.5 are indicative of poor reliability, values between 0.5 and 0.75 indicate moderate reliability, values between 160 161 0.75 and 0.9 indicate good reliability, and values greater than 0.90 indicate excellent reliability (8). To determine concurrent validity, a Pearson correlation analysis was also 162 performed between OptoGait[™] and Stryd[™] data. The following criteria were adopted to 163

164	interpret the magnitude of correlations between measurement variables: <0.1 (trivial),
165	0.1-0.3 (small), 0.3-0.5 (moderate), 0.5-0.7 (large), 0.7-0.9 (very large) and 0.9-1.0
166	(almost perfect) (7). Pairwise comparisons of means (t-test) were also conducted between
167	data (CT, FT, SL, and SF) from the two devices (OptoGait [™] and Stryd [™]) at different
168	running speeds (8-20 km.h ⁻¹). Additionally, the magnitude of the differences between
169	values were also interpreted using the Cohen's d effect size (ES) (19). Effect sizes of less
170	than 0.4 represented a small magnitude of change while 0.41-0.7 and greater than 0.7
171	represented moderate and large magnitudes of change, respectively (19). The level of
172	significance used was p<0.05. Data analysis was performed using SPSS (version 21,
173	SPSS Inc., Chicago, Ill).
174	
175	Results
176	
177	Reliability
178	Table 1 shows the CV (as a measure of absolute reliability) of spatio-temporal parameters
179	at different running velocities from both $Stryd^{TM}$ and $OptoGait^{TM}$. For the $Stryd^{TM}$ system,
180	CV ranged between 1.2-2.3% (CT), 3.7-11.6% (FT), 1.1-2.1% (SL) and 1.1-2.0% (SF);
181	whereas for the OptoGait [™] system, CV was 2.3-3.0% (CT), 6.0-30.6% (FT), 2.0-3.8%
182	(SL) and 2.2-3.6% (SF). Additionally, the SEM is provided in Table 2.
183	TABLE 1 ABOUT HERE
184	TABLE 2 ABOUT HERE
185	
186	Validity
187	The Pearson correlation analysis is shown in Table 3 (CT, FT, SL, and SF or cadence at
188	8-20 km.h ⁻¹ running velocities). CT from both devices showed large correlations (0.5-0.7,

189	p<0.05) at low speeds (8-11 km.h ⁻¹) and race speeds (14-16 km.h ⁻¹). FT from OptoGait [™]
190	and Stryd TM showed large and very large correlations, respectively ($0.602 < r > 0.834$,
191	p < 0.05) over the velocities tested (8-20 km.h ⁻¹). SL and SF from both devices were nearly
192	perfectly correlated ($r > 0.9$, $p<0.001$) at every running velocity tested.
193	TABLE 3 ABOUT HERE
194	
195	The ICCs between kinematic variables from both Stryd vs. OptoGait systems over the
196	entire protocol (8-20 km.h ⁻¹) are included in Table 4. CT showed a low coefficient (<0.5),
197	FT a moderate coefficient (0.5-0.75), whereas SL and SF showed excellent coefficients
198	(>0.9).
199	TABLE 4 ABOUT HERE
200	
201	A paired t-test demonstrated some significant differences ($p<0.05$) and large ES (>0.7) in
202	the variables analysed (CT, FT, SL, and cadence) (Figures 1-4, respectively). CT (Figure
203	1) was underestimated for Stryd [™] compared to OptoGait [™] data (8-18 km.h ⁻¹ , p<0.001 and
204	ES>0.7; ~6-8%). Differences were smaller at 19 km.h ⁻¹ (p<0.05 and ES>0.7; ~4%) and
205	no differences were observed at 20 km.h ⁻¹ (p \ge 0.05 and ES<0.1; ~0.5%).
206	FIGURE 1 ABOUT HERE
207	
208	FT (Figure 2) was overestimated for Stryd [™] based on OptoGait [™] data at running
209	velocities between 8-19 km.h ⁻¹ (p<0.05, ES>0.7; from ~65% at 8 km.h ⁻¹ to ~7% at 19
210	km.h ⁻¹). No significant differences were found at 20 km.h ⁻¹ ($p \ge 0.05$ and ES=0.57; ~3%).
211	FIGURE 2 ABOUT HERE
212	

SL from both devices is shown in Figure 3. P-values show significant differences
(p<0.05) between data from Stryd[™] and OptoGait[™] at most analysed velocities, although
Cohen's d showed a very small magnitude of changes (ES<0.1), with Stryd[™] data
overestimated compared to OptoGait[™] data (<1%). Likewise, significant differences
(p<0.05) were found in cadence between the two devices (Figure 4) but Cohen's d
reported a very small change (ES<0.1) with differences smaller than 1%.

219

FIGURES 3 AND 4 ABOUT HERE

221

220

222 Discussion

This study aimed to determine the absolute reliability and to evaluate the concurrent 223 validity of the Stryd[™] system for measuring spatio-temporal variables during running at 224 225 different velocities (8-20 km.h⁻¹) by comparing data with a device widely-used for this purpose (OptoGait system[™]). The major findings of this study were: (i) CV, as a measure 226 of reliability, was lower in all analysed variables for the Stryd[™] system than for the 227 228 OptoGait[™] system (<5% in all cases, except for FT), while SEM was almost identical for every variable over the entire protocol (8-20 km.h⁻¹); (ii) concurrent validity of the Stryd[™] 229 and OptoGait[™] systems regarding spatio-temporal variables is not yet settled: moderate 230 231 for CT, low for FT, and very high for SL and SF. Results from Pearson correlation analysis indicated a strong concurrent validity over the entire range of running velocities 232 (8-20 km.h⁻¹), with large correlations in CT, very large correlations in FT and almost 233 234 perfect correlations in SL and SF. The ICCs partially provide support to those results with excellent coefficients for SL and SF and moderate for FT, but poor coefficients for CT 235 236 (over the entire protocol). Additionally, the paired t-test let us improve our comparison and some interesting findings are worth noting: (i) The Stryd[™] system underestimated CT 237

(up to ~8% at low velocities) and overestimated FT (up to ~65% at low velocities)
compared with the OptoGait system[™], with reduced differences at high running
velocities; (ii) despite differences in p-values, the very small magnitude of changes
reported suggests that SL and SF (from the Stryd[™] system) are valid variables over
running velocities of 8-20 km.h⁻¹, compared with the OptoGait[™] system.

243

244 As mentioned earlier, scientists have discovered the potential of accelerometers (and 245 inertial measurement units, IMUs) in assessing gait analysis without the restrictions of laboratory technology. Having the chance to measure athletes or clients in a natural 246 247 environment and using less expensive and more time-efficient equipment is a huge step forward for coaches and clinicians. Nevertheless, this advantage would be worthless if 248 the data were not valid. The Stryd[™] system (based on a 6-axis inertial motion sensor: 3-249 250 axis gyroscope, 3-axis accelerometer) is mainly a running power meter, but it also 251 provides spatio-temporal variables that are used by coaches and clinicians (information 252 easily accessible to users) as a feedback, necessitating confirmation of the validity of 253 these data.

254

255 Comparing between devices and technologies (i.e., photoelectric cells vs. IMUs), the 256 authors hypothesize that differences in temporal variables might be at least partially explained by the height of the OptoGait system[™]'s LED diodes. As described by Lienhard 257 et al. (10), the LED diodes of the OptoGait[™] system are positioned 3 mm above ground 258 259 and thereby, sensing of heel contact occurs earlier, whereas sensing of toe lift-off occurs 260 later in the gait cycle (timing differences). In a similar previously published study (4), the 261 authors assessed the reliability and validity of an accelerometer-based system (Myotest®) against a photocell-based system (OptoJump[™]) for measuring running stride kinematics. 262

In line with our data, the authors reported CT 34% shorter and FT 64% longer than the photocell-based system. That work (4) also found a good validity in SF. Therefore, the data obtained in the current study agree with those reported by previous studies that compared accelerometer-based systems to photocell-based systems, and our results support the explanation for this discrepancy given by Lienhard et al. (10).

268

269 Some final limitations need to be taken into consideration. First, the use of photocell-270 based systems as the gold standard reference for establishing concurrent validity should be evaluated, instead of instruments that measure ground reaction force, such as a force 271 272 platform. Because we do not possess such equipment in our laboratory, the use of the OptoGait system was considered to be an adequate proxy system given its demonstrated 273 274 good validity compared to GAITRite system® -pressure platform- (9) or compared to 275 force platform during jumping tests (5). Furthermore, the OptoGait system[™] is more 276 practical and portable for recording several consecutive steps than force or pressure 277 platforms imbedded into the ground in series where participants often have to adjust SL 278 and target platforms to obtain clearly defined foot contact data. A second consideration is that validation data were obtained from an analysis based on within-subject variation 279 280 (CV) rather than on different days. Although the number of steps analysed in 3-min of 281 running at these velocities is high (400-500 steps in 3 min), our current reliability statistics 282 might not generalise to runs performed several days apart.

283

284 Conclusion

To sum up, based on traditional thresholds, the absolute (i.e., CV) reliability of CT, FT,
SL, and SF derived using the Stryd[™] device were classified as adequate for running
assessments, and this suggests that the Stryd[™] is useful for monitoring individuals and

quantifying changes in functional performance over time. However, the concurrent
validity of Stryd[™] as compared to OptoGait[™] was low-moderate for CT and FT, and
excellent for SL and SF. The paired comparisons added to those correlations showed that
the Stryd[™] system underestimated CT (0.5-8%) and overestimated FT (3-67%) compared
with OptoGait[™] system, with reduced differences at elevated running velocities (8-20
km.h⁻¹). On the other hand, SL and SF were valid variables (<1%) over the entire range
of running velocities, as compared with the OptoGait[™] system.

295

296 *Practical applications*

From a practical point of view and considering that both systems are widely used, scientists and clinicians should know that both devices showed an adequate reliability for running assessments and, thereby, spatio-temporal parameters reported from these devices can be compared over time (if using the same device). However, the clients also should be aware about the limitations of comparing data reported from these two devices.

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Figure 1. Contact time (s) during running measured by Stryd[™] and OptoGait[™] systems.

*p<0.05, **p<0.01, ***p<0.01



371 Figure 2. Flight time (s) during running masured by $Stryd^{TM}$ and $OptoGait^{TM}$ systems.

*p<0.05, **p<0.01, ***p<0.01



Figure 3. Step length (cm) during running measured by Stryd[™] and OptoGait[™] systems.

*p<0.05, **p<0.01, ***p<0.01



379 Figure 4. Step frequency (cadence, step/min) during running measured by Stryd[™] and

380 OptoGaitTM systems. p<0.05, p<0.01, p<0.01

381	Table 1. Coefficient of variation (%) of the spatio-temporal parameters (CT, FT, SL and
382	SF) at different running velocities (8-20 km.h ⁻¹) from OptoGait system and from Stryd

383 system.

Speed	Contact	time (CT)	Flight	time (FT)	Step ler	ngth (SL)	Step freq	uency (SF)
(km.h ⁻¹)	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait
8	1.46	3.01	11.60	30.58	1.32	3.78	1.31	3.13
9	1.38	2.91	9.38	24.17	1.38	3.61	1.33	3.30
10	1.53	2.90	7.35	18.62	1.22	3.39	1.19	3.14
11	1.43	2.79	5.78	14.01	1.13	3.28	1.11	3.06
12	1.37	2.59	5.21	11.44	1.24	3.04	1.19	2.77
13	1.22	2.56	4.27	9.05	1.09	2.74	1.05	2.79
14	1.27	2.48	4.18	8.26	1.14	2.63	1.13	2.52
15	1.34	2.41	4.29	7.05	1.33	2.24	1.26	2.35
16	1.91	2.53	4.59	6.46	1.20	1.98	1.17	2.33
17	1.56	2.38	3.73	6.38	1.32	2.02	1.29	2.30
18	1.98	2.33	5.11	6.37	1.86	2.08	1.69	2.15
19	2.23	2.45	5.39	6.41	2.02	2.24	1.87	2.27
20	2.32	2.48	7.56	6.01	2.08	2.66	2.01	3.54

	386	Table 2. St	andard error	of mean	(SEM)	of the	spatio-te	emporal	parameters	(CT,	FT,	SL
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and SF) at different running velocities (8-20 km.h⁻¹) from OptoGait system and from

388 Stryd system.

Speed	Contact	time (CT)	Flight	time (FT)	Step le	ngth (SL)	Step frequency (SF)		
(km.h ⁻¹)	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait	Stryd	OptoGait	
8	0.005	0.005	0.008	0.009	1.345	1.259	2.483	2.269	
9	0.004	0.005	0.007	0.009	1.228	1.179	2.138	2.068	
10	0.003	0.004	0.005	0.007	1.071	1.032	1.746	1.777	
11	0.003	0.003	0.005	0.007	1.479	1.539	2.213	2.234	
12	0.003	0.003	0.005	0.007	1.572	1.539	2.227	2.229	
13	0.003	0.002	0.004	0.005	1.583	1.497	2.108	2.103	
14	0.003	0.002	0.004	0.005	1.704	1.757	2.198	2.179	
15	0.002	0.002	0.003	0.004	1.794	1.730	2.207	2.164	
16	0.002	0.002	0.003	0.004	1.930	1.881	2.318	2.355	
17	0.002	0.002	0.003	0.004	2.146	2.151	2.507	2.529	
18	0.001	0.002	0.004	0.004	2.412	2.484	2.771	2.787	
19	0.001	0.002	0.003	0.003	2.252	2.278	2.535	2.591	
20	0.001	0.003	0.003	0.003	2.013	2.079	2.211	2.406	

Table 3. Pearson correlation between kinematics variables from Stryd vs. Optogait over an incremental running test (8-20 km.h⁻¹).

Speed (km.h ⁻¹)	8	9	10	11	12	13	14	15	16	17	18	19	20
Contact time	0.657**	0.636**	0.574*	0.525*	0.433	0.435	0.507*	0.504*	0.503*	0.453	0.415	0.429	0.078
Flight time	0.602**	0.656**	0.685**	0.703**	0.722**	0.739***	0.722***	0.782***	0.811***	0.800***	0.775***	0.680*	0.834*
Step length	0.934***	0.999***	0.999***	0.999***	0.999***	0.998***	0.997***	0.998***	0.999***	0.999***	0.999***	0.997***	0.991***
Step frequency	0.959***	0.996***	0.999***	0.999***	0.999***	0.999***	0.999***	0.999***	0.999***	0.999***	0.999***	0.999***	0.999***

* p<0.05; ** p<0.01; *** p<0.001

Table 4. Intra class correlation coefficients (ICC) between kinematics variables from Stryd vs. Optogait over an incremental running test (8-20 km.h⁻¹).

Speed (km.h ⁻¹)	8	9	10	11	12	13	14	15	16	17	18	19	20
Contact time	0.457	0.463	0.416	0.386	0.303	0.330	0.407	0.400	0.380	0.329	0.294	0.381	0.063
Flight time	0.555	0.599	0.655	0.679	0.702	0.726	0.758	0.768	0.799	0.778	0.744	0.635	0.806
Step length	0.934	0.998	0.999	0.999	0.999	0.998	0.997	0.998	0.999	0.999	0.999	0.997	0.991
Step frequency	0.956	0.995	0.999	0.999	0.999	0.999	0.999	0.999	0.999	0.999	0.999	0.997	0.983