- 1 **Title:** Surface-Parallel Sensor Orientation for Assessing Energy Balance
- 2 Components on Mountain Slopes
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- 4 Source: Boundary-Layer Meteorology Volume: 158 Issue: 3 Pages: 489-
- 5 499 **Published:** 2016
- 6 **DOI:** 10.1007/s10546-015-0099-4
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#### Surface-parallel sensor orientation for assessing energy 8 balance components on mountain slopes 9

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14 Received: DD Month YEAR/ Accepted: DD Month YEAR

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Abstract The consistency of eddy-covariance measurements is often evaluated in terms 16 17 of the degree of energy balance closure. Even over sloping terrain, instrumentation for 18 measuring energy balance components are commonly installed horizontally, i.e. 19 perpendicular to the geo-potential gradient. Subsequently, turbulent fluxes of sensible 20 and latent heat are rotated perpendicular to the mean streamlines using tilt correction 21 algorithms. However, net radiation  $(R_n)$  and soil heat fluxes (G) are treated differently, 22 and typically only  $R_n$  is corrected to account for slope. With an applied case study, we 23 show and argue several advantages of installing sensors surface-parallel to measure 24 surface-normal  $R_n$  and G. For a 17% southwest-facing slope, our results show that 25 horizontal installation results in hysteresis in the energy balance closure and errors of up 26 to 25%. Finally, we propose an approximation to estimate surface-normal  $R_n$ , when only 27 vertical  $R_n$  measurements are available.

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29 Keywords Energy balance closure • Hysteresis • Net radiation• Soil heat flux • Sloping 30 terrains

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# 55 **1 Introduction**

56 Measurements of turbulent fluxes in varying environments are one of the tools scientists 57 and decision makers rely on for assessing and forecasting global warming (Kaminski et 58 al. 2012, Koffi et al. 2013). Thus, eddy-covariance towers have proliferated around the 59 world in the last two decades (FLUXNET tower network; Baldocchi et al. 2001). Since 60 ideal sites are rarely found worldwide, there was a great need to extend the applicability 61 of the eddy-covariance method to situations over non-ideal (or "complex") terrain. 62 Different studies even concluded that the eddy-covariance method can be used over 63 sloping terrain to evaluate energy and CO<sub>2</sub>/H<sub>2</sub>O fluxes of whole ecosystems (Hammerle 64 et al. 2007, Hiller et al. 2008). However, general problems of the eddy-covariance 65 method are aggravated by sloping terrain. Both the error induced by neglecting vertical 66 and horizontal advective fluxes (Aubinet et al. 2003, Aubinet et al. 2005) and the 67 underestimation of night-time ecosystem respiration during stable night-time conditions (Gu et al. 2005, Aubinet 2008) depend critically on slope, although such problems are 68 69 less pronounced over short vegetation.

70 One of the most commonly used methods for evaluating the consistency of eddy-71 covariance turbulent flux measurements is to assess closure of the energy balance 72 (Wilson et al. 2002, Stoy et al. 2013). This quality control criterion for eddy-covariance 73 measurements consists of comparing the sum of the latent (LE) and sensible (H) heat 74 fluxes, measured with the eddy-covariance method, to the available energy consisting of 75 net radiation  $(R_n)$  minus the soil heat flux (G). According to the first law of 76 thermodynamics, incoming and outgoing energy components must balance one another. 77 This independent assessment of eddy-covariance measurement reliability has been 78 evaluated for many FLUXNET sites with a mean imbalance on the order of 20% 79 (Wilson et al. 2002). The reasons for the general imbalance remain unclear and are under discussion (Foken 2008, Leuning et al. 2012, Stoy et al. 2013), and turbulent 80 81 fluxes are often considered "acceptable" when the energy balance residual does not 82 exceed 30%. Over sloping terrain, the energy budget quality control yields results 83 comparable to those for sites located in more ideal terrain (Hammerle et al. 2007, Hiller 84 et al. 2008, Etzold et al. 2010). In the following, we focus on ecosystem-scale 85 exchanges over a mountain slope that is quasi-uniform across and beyond the source 86 area (footprint) of the flux measurements. That is, we focus on the effect of the average

87 slope over scales of hectares on the energy balance. Smaller undulations that can even 88 exist within flat terrain (such as ploughed farmlands) are not the subject of this study 89 and are addressed elsewhere (Wohlfahrt and Tasser 2014).

90

Overall, the goal of an energy balance study must be to represent all contributing 91 terms in the same way that they influence the exchange surface. This can be achieved by 92 minimizing the incident angle between a contributing term and its measurement 93 regardless of the exchange surface orientation. Atmospheric turbulence results in down-94 gradient transport by turbulent diffusion, with the "exchange" coordinate of the scalar 95 flux being perpendicular to the streamlines/surface. For radiation components, both the 96 irradiance and emittance relevant to the surface are clearly in the normal direction, 97 irrespective of the geopotential gradient (this is why solar panels are not installed 98 horizontally). Such net radiative effects also establish isotherms parallel to the surface 99 and soil temperature gradients in the surface-normal direction, which is therefore the 100 relevant direction to measure G.

101 Over sloping sites, eddy-covariance systems are typically installed horizontally 102 and the resulting fluxes H and LE are subsequently rotated perpendicular to the mean 103 streamlines. However, the  $R_n$  and G terms contributing to the energy balance are treated 104 differently. Net radiometers are installed horizontally and either (a) no rotation is 105 applied (e.g., Etzold et al. 2010) or (b) the incoming solar radiation component of the 106 net radiation is corrected for the inclination, arguing that this is the most important 107 component contributing to  $R_n$  (Matzinger et al. 2003, Hammerle et al. 2007, Hiller et al. 108 2008, Saitoh et al. 2011). Oftentimes no information is provided on the alignment of the 109  $R_n$  and G sensors.

110 This study examines the advantages of installing the net radiometer and soil heat flux 111 instruments parallel to the average slope. Section 2 provides information on the study 112 site and the sensor deployments. In Sect. 3, we present the case study results of 113 horizontal vs. parallel sensor installations, and propose an approximation to estimate 114 surface-normal  $R_n$ , when only vertical  $R_n$  measured with horizontally oriented (i.e., 115 level) sensors is available. Finally, in Sect. 4 and 5 we discuss our findings and provide 116 concluding recommendations.

# 118 2 Methods

#### 119 2.1 Site description

120 The experimental part of the study was conducted in the Sierra Nevada National Park in 121 south-eastern Spain (36°58'3.68"N; 3°28'37.04"W, 2320 m a.s.l.; Fig 1). Vegetation 122 consists of grass and forbs (Genista versicolor, Festuca spp. and Sessamoidesprostata, 123 dominant species) recovering in the wake of a 2005 wildfire. Given the short vegetation 124 and the aerodynamically simple surface, the contribution of air storage to net exchanges 125 is very small and thus neglected (Suyker and Verma 2001, Kowalski et al. 2003). An 126 eddy covariance tower was installed in 2009 over an averaged slope of 17% of 127 southwest (255°) aspect. Previous studies showed that fluxes typically originate from 128 source areas within approximately 300 m of the tower (Serrano-Ortiz et al. 2011).

129

## 130 2.2 Sensor deployments

131 The following analyses were performed on data from 7 July to 20 August of 2010, with 132 34 days under cloud-free conditions and 10 partially cloudy days; no fully overcast 133 conditions occurred. During this period the eddy-covariance tower measured turbulent 134 exchanges of energy between the surface and the atmosphere. Sensible (H) and latent 135 (LE) heat fluxes were calculated from fast-response (10 Hz) instruments (Infrared gas 136 analyser Li-7500, Lincoln, NE, USA; three-axis sonic anemometer Model 81000, R.M. 137 Young, Traverse City, MI, USA; mounted horizontally so that "w" represents the 138 vertical wind; valid operating range for attack angle in the range  $\pm 60^{\circ}$ ) mounted atop a 139 6-m tower.

140 Means, variances and covariances were calculated for half-hour periods following 141 Reynolds' rules, and eddy flux corrections for density perturbations (Webb et al. 1980) 142 and tests for stationarity and turbulence development tests were applied using the 143 EddyPro 5.1.1 software. The stationarity test compares the covariances determined for 144 the half hourly period and for shorter intervals within this period (usually 5 minutes). A 145 time series is considered to be steady state if the difference between both covariances is 146 lower than 30% (Mauder and Foken 2004). The turbulence development was tested by 147 using the so-called flux-variance similarity where the ratio of the standard deviation of a 148 turbulent parameter and its turbulent flux (measured parameter) is a function of the 149 stability (modelled parameter). Well developed turbulence can be assumed if the 150 difference between the measured and the modelled parameter is lower than 30%

151 (Mauder and Foken 2004). After applying both tests, the EddyPro 5.1.1 software 152 provides the flag "0" for high quality fluxes (differences <30% for both test), "1" for 153 intermediate quality fluxes (differences <30% for one test) and "2" for poor quality 154 fluxes (differences >30% for both test).

155 Since no systematic error has been observed for applying different rotation methods 156 over sloped sites (e.g., Turnipseed et al. 2003, Shimizu 2015) and particularly for our 157 experimental site (double rotation vs planar fit showed no significant differences, data 158 not shown), the double coordinate rotation was used to ensure that the rotated average 159 "w" is zero in the direction normal to the surface. While double rotation of half hourly 160 data is one of the most common methods used, it is frequently cited inadequately: the 161 often-cited paper by McMillen (1988) relied on erroneous equations from a grey-162 literature report by Tanner and Thurtell (1969). The correct version was first provided 163 by Kowalski et al. (1997) and is now also frequently cited via Aubinet et al. (2000).

164 In addition to the turbulent fluxes, available energy was determined by duplicate 165 sensors in two configurations, one parallel to the surface and the other horizontal. For 166 each, a net radiometer (NR Lite, Kipp&Zonen, Delft, Netherlands) was located 2 m above the surface, and two heat flux plates (HFP01SC, Hukseflux, Delft, Netherlands) 167 168 were installed at 8 cm depth, with two pairs of soil temperature probes (TCAV, 169 Campbell Scientific, Logan, UT, USA) at 2 and 6 cm depth, and a water content 170 reflectometer (CS616, Campbell Scientific, Logan, UT, USA) at 4 cm depth. The soil 171 heat flux (G) was calculated by adding the measured heat flux at a fixed depth (8 cm) 172 under bare soil to the energy stored in the layer above the heat flux plates, based on the 173 specific heat capacity of the soil and changes in the temperature and soil water content 174 with time (Massman 1992, Domingo et al. 2000). Finally, the incident and reflected 175 photosynthetic photon flux densities (PPFD) were measured by quantum sensors (Li-176 190, Lincoln, NE, USA) to identify the partially cloudy days and estimate the surface 177 albedo.

178

### 179 **2.3** *Modelling*

Following Olmo et al. (1999), the surface-normal  $R_n$  was modelled based on vertical  $R_n$ measurements. First, vertical daytime  $R_n$  values were converted to global irradiance ( $R_g$ ), defined as the total amount of shortwave radiation (direct+diffuse; W m<sup>-2</sup>) received from above by a surface (Iqbal 1983), using the linear relationship between  $R_n$  and  $R_g$ evaluated by Alados et al. (2003) for semi-arid sites:

$$R_n = a R_g + b, \tag{1}$$

186 where a=0.709 and b=-25.4 W m<sup>-2</sup>.

189

208

187 Secondly, the daytime surface-normal  $R_g$  was modelled following Olmo et al. 188 (1999)

$$R_{g\psi} = R_g exp(-k_t(\psi^2 - \theta_z^2)) F_c \quad (day)$$
<sup>(2)</sup>

190 where  $R_{g\psi}$  is the global irradiance on the inclined surface,  $R_g$  is the global irradiance on 191 the horizontal surface,  $\psi$  is the angular distance (in radians) from the surface normal to 192 the sun's position,  $\theta_z$  denotes the solar zenith angle,  $k_t$  is the clearness index,  $F_c$  is a 193 multiplying factor to take into account anisotropic reflections.

194 The angular distance  $\psi$  can be evaluated as follows:

195 
$$\cos \psi = \sin \alpha \sin \alpha_s + \cos \alpha \cos \alpha_s \cos(\varphi_s - \varphi),$$
 (3)

196 where  $\alpha$  is the angle of the slope (surface elevation) with respect to the horizontal 197 surface,  $\alpha_s$  is the sun elevation angle with respect to the horizontal surface,  $\varphi_s$  is the sun 198 azimuth and  $\varphi$  the surface azimuth (Fig. 2).

199The clearness index can be evaluated as follows:

$$K_{\rm t} = R_{\rm g}/R_{\rm gext},\tag{4}$$

201 where  $R_{\text{gext}}$  is the extraterrestrial irradiance calculated as follow (Iqbal, 1983):

202 
$$R_{\text{gext}} = I_{\text{sc}} (r_0/r)^2 \cos \theta_z, \qquad (5)$$

where  $I_{sc}$  is the solar constant (1367 W m<sup>-2</sup>),  $r_0$  is the average sun-earth distance and r is the real sun-earth distance according to day of year.

205 Concerning the anisotropic correction factor,  $F_c$ , we have tested various types of 206 functions and obtained the best agreement between the computed and observed 207 radiation values as follows:

$$F_{\rm c} = \sin \psi (1/(0.55 - \rho)),$$
 (6)

209 where  $\rho$  is the surface albedo, approximated as the ratio of the averaged daytime 210 reflected to incident PPFD for the studied period ( $\rho$ = 0.12).

211 Thirdly, the obtained results were converted into surface-normal Rn values 212  $(R_{n\psi})$ , using again the site-specific linear regression (1).Finally, the nighttime values of 213 surface-normal  $R_n$  were directly modelled as follow:

214 
$$R_{n\psi} = R_n \cos \alpha_s. \tag{7}$$

In contrast to the  $R_n$  measurement, the vector components of the soil heat flux are not known. Also, unlike the turbulence sensors the soil heat flux plate measures only along a single axis. Consequently, no correction was attempted for transforming vertical Ginto a surface-normal coordinate.

219

# 220 **3 Results**

Data are reported using Coordinated Universal Time (UTC), which leads local solartime at this site by less than 15 minutes.

223 For our study case, vertical  $R_n$  and G measured with horizontal sensor 224 orientation underestimate available energy due to the slight southern aspect of the slope, 225 with the expected delay in the maxima due to the predominantly western aspect (Fig. 226 3a). Significant differences between morning and afternoon values and daily totals of  $R_n$ 227 and G were measured comparing both orientations. The radiometer installed horizontally overestimated morning  $R_n$  by around 100 Wm<sup>-2</sup> and underestimated 228 afternoon values by around 150 Wm<sup>-2</sup>, resulting in 21% and 16% underestimation of the 229 230 daily means under cloud-free and partially cloudy conditions respectively (Fig. 3). 231 Similarly, horizontally installed soil heat flux plates overestimated morning values by around 25 Wm<sup>-2</sup> and underestimated afternoon values by 40 Wm<sup>-2</sup>, leading to an overall 232 233 underestimation of 13% in the daily totals under cloud free conditions; no 234 underestimation was observed under partially cloudy conditions (Fig. 3c).

This results in clear hysteresis in energy balance closure when vertical  $R_n$  and G 235 236 values from horizontal sensors were used (Fig. 4a and 5a). Maximum values of vertical 237  $R_n$  and G were measured at noon, whereas for rotated H and LE peaks occurred in late 238 afternoon (Figure 5a). The situation is resolved when sensors are installed parallel to 239 the slope measuring surface-normal  $R_n$  and G. Peak values of all components of the 240 energy balance occurred in late afternoon, in accordance with the south-western aspect 241 of the slope (Fig. 5f), improving both the slope (from 1.20 to 1.06; Fig. 4f) and the 242 explained variance ( $\mathbb{R}^2$  from 0.83 to 0.99; Fig 4f) of the linear least-squares regression. 243 When vertical G is measured with horizontal sensor orientation (Fig. 5c), the energy 244 balance closure (regression slope) does not change substantially, but scatter of around 100 Wm<sup>-2</sup> increases (Fig. 4c). When the modelled surface-normal  $R_n$  is used (Fig 5b and 245 e), the regression fit is also improved ( $R^2=0.92$ ; Fig. 4b and e). Note that, despite the 246 247 good match between measured and modelled surface-normal  $R_n$  (slope=1.009±0.005, yintercept=-2 $\pm$ 1, R<sup>2</sup>=0.96; *n*=1983), the comparison of daily patterns shows clear 248 249 mismatches at sunrise, sunset and midday (Fig. 3). Under cloud-free conditions (Fig. 3a) modelled surface-normal  $R_n$  overestimated sunrise and midday values by around 70 Wm<sup>-2</sup> and similarly underestimated sunset values. Under partially cloudy conditions (Fig. 3c), modelled surface-normal  $R_n$  yielded clearly overestimated values from 0900 to 1700 UTC by up to 135 Wm<sup>-2</sup>. This results in a deviation from the energy balance closure 1:1 line between 100 Wm<sup>-2</sup> and 300 Wm<sup>-2</sup> when considering the whole database (Fig. 4b, 4e), and 6% underestimation and 20% overestimation in the daily mean for sunny and partially cloudy days respectively (Fig. 3a and c).

257

# 258 **4 Discussion**

259 Our case study confirms improved energy balance closure when both the net radiometer 260 and soil heat flux instruments were installed parallel to the slope compared to other 261 configurations, such as horizontal or modelled normal-surface  $R_n$ . For the case of G, 262 with modest contribution to the energy balance, parallel installation did not substantially 263 improve the slope, but did reduce the scatter. It needs to be considered that G264 measurements only represent their immediate environment (of order  $0.01 \text{ m}^2$ ) whereas radiation and turbulent flux measurements represent of order 100 m<sup>2</sup> and 1000 m<sup>2</sup>, 265 266 respectively, for these measurement heights. Hence, for representing a spatial scale 267 more comparable to the radiation and flux measurements, a population of soil plates 268 placed parallel to the average slope is required.

269 Since  $R_n$  represents more than 70% of available energy, it is commonly accepted by the FLUXNET community to install radiometers horizontally and approximate 270 271 surface-normal R<sub>n</sub> following trigonometric corrections in post-processing, but to neglect 272 the effect of the slope on G (Hammerle et al. 2007, Hiller et al. 2008, Zitouna-Chebbi et 273 al. 2012). If such an approximation is to be performed reliably, not only net radiometers but also pyranometers should be installed to distinguish the total, direct and diffuse 274 275 shortwave radiation components. In such a way, direct shortwave radiation can be easily 276 corrected for slope effects knowing the azimuthal and elevation angles, latitude and 277 surface inclination (Garnier and Ohmura 1968, Whiteman et al. 1989). Since direct 278 shortwave radiation represents from 60 to 80% of  $R_n$  for mid-latitudes, and is the 279 component most affected by slope effects (Holst et al. 2005), such post-processing 280 correction typically yields acceptable results. However, according to Oliver (1992), 281 under partially cloudy conditions, information about cloud cover and opacity is required 282 and the correction quickly becomes either complex or inaccurate. Moreover, not only

283 the direct but also the reflected shortwave radiation component (from 5 to 15% of the 284 total  $R_n$ ) is affected by the slope (Holst et al. 2005). Additionally, our results show that, under cloud-free conditions, approximating surface-normal  $R_n$  is justified when stations 285 286 measure only  $R_n$  and not its components. However, under partially cloudy conditions the 287 model clearly overestimated  $R_n$ . Unfortunately, fully overcast conditions were lacking 288 during our experiment, and we cannot evaluate the model performance on cloudy days. 289 Furthermore, a site-specific linear regression relationship is required as an intermediate 290 step to convert the measured  $R_n$  into global irradiance and vice versa.

291 While in the immediate air layer above an exchange surface, net-transport is down-292 gradient, i.e. surface-normal, there are also relevant cases for examining vertical 293 exchange of heat: with increasing distance from the exchange surface, some types of 294 atmospheric flows are dominated by buoyancy. In this case the relevant direction of 295 transport is vertical, following the geopotential gradient. For example, when studying 296 atmospheric stability, the vertical exchange of heat (or actually: buoyancy) must be 297 considered. This implies the need to consider vertical buoyancy fluxes when calculating 298 the Richardson number, for example, irrespective of surface orientation.

299

# **300 5 Conclusion and recommendations**

301 For energy balance studies the transport direction of interest is surface-normal. 302 Consequently, for assessing the energy balance over a sloping surface without complex 303 local topography or undulations, we recommend installing the net radiometer and soil 304 heat flux plates parallel to the average slope. For other uses, such as validation of 305 regional models using the energy fluxes measured at the ecosystem scale, spatial 306 aggregation beyond differing definitions of the exchange direction needs to be 307 considered. Equally important, slope and aspect lead to distinct differences in the 308 ecosystem types, necessitating a careful evaluation of spatial representativeness of the 309 measured fluxes.

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- 311

## 312 Figures



313

314 Fig 1 Measurement site on the south-western slope of the Sierra Nevada National Park, Spain (Tower not

- to scale.). Source: Google Earth, 36°58'3.68''N; 3°28'37.04''W, image: Landsat, imagery date August 4,
- 316 2012, accessed November 9, 2014.



**Fig 2** Sketch of the angles involved in the radiation model. Angular distance (in radians) from the surface normal (n') to the sun's position ( $\psi$ ); solar zenith angle ( $\theta_z$ ); angle of the slope (surface elevation) with

- 320 respect to the horizontal surface ( $\alpha$ ), sun elevation angle respect to the horizontal surface ( $\alpha_s$ ), sun
- 321 azimuth ( $\varphi_s$ ), surface azimuth ( $\varphi$ ).





324 Fig 3 Daily patterns of the energy balance components under cloud-free (a, b) and partially cloudy (c, d) 325 conditions. Vertical radiation  $(R_n)$  and soil heat flux (G) measured with horizontal sensor orientation 326 (subscript "v"; dark gray symbols), surface-normal Rn and G measured with surface-parallel sensor 327 orientation (subscript "sn"; black symbols) and modelled surface-normal  $R_n$  (subscript " $\psi$ "; light gray 328 circles) for panels a) and c). Surface-normal sensible (H) and latent heat (LE) fluxes for panels b) and d). 329 Each point represents the hourly ensemble value for the fourth week of August 2010 ( $\pm$ SD). Open 330 symbols for panel b) represent points with <60% of data with quality flag "0" following Mauder and 331 Foken (2011).



332

Fig 4 Energy balance closure for different energy sensor combinations: net radiation ( $R_n$ ), soil heat flux (G) and surface-normal sensible (H) and latent (LE) heat fluxes. Each point represents the hourly ensemble value ( $H+LE vs. R_n+G$ ) for the entire measured period combining cloud-free and partially cloudy days (±SD). Information about the slope, *y*-intercept and R<sup>2</sup> is provided.





**Fig 5** Daily patterns of the energy balance components for different energy sensor combinations:net radiation ( $R_n$ ), soil heat flux (G) and surface-normal sensible (*H*) and latent (*LE*) heat fluxes. Each point represents the hourly ensemble value of the different energy components for the entire measured period combining cloud-free and partially cloudy days (±SD). Open circles represent points with<60% of data with quality flag "0" following Mauder and Foken (2011).

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345 Acknowledgements We wish to thank for their critical opinions and valuable comments that inspired this 346 manuscript: Edward Ayres, Robert Clement, Thomas Foken, Hongyan Luo, Harry McCaughey, 347 NatchayaPingintha-Durden, and Jielun Sun. This research was funded in part by the Andalusia Regional 348 Government through projects P12-RNM-2409 and P10-RNM-6299, by the Spanish Ministry of Economy 349 and Competitiveness though projects CGL2010-18782, CGL2014-52838-C2-1-R (GEISpain) and 350 CGL2013-45410-R; and by European Community's Seventh Framework Programme through INFRA-351 2010-1.1.16-262254 (ACTRIS), INFRA-2011-1-284274 (InGOS) and PEOPLE-2013-IOF-625988 352 (DIESEL) projects. The National Ecological Observatory Network is a project sponsored by the National 353 Science Foundation and managed under cooperative agreement by NEON, Inc. This material is based 354 upon work supported by the National Science Foundation under the grant DBI-0752017. Any opinions, 355 findings, and conclusions or recommendations expressed in this material are those of the author(s) and do 356 not necessarily reflect the views of the National Science Foundation.

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